

Clutching a Grip on AUTOSAR using Haskell

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Tool-neutral

Platform-neutral

Vendor-neutral

Component architecture

Automotive domain

Development methodology

Industry standard

AUTOSAR

Distribution

Real-time

OS kernel

I/O abstraction

Concurrency

Standard library

Communication

Black box interoperability

Standardized interfaces

The AUTOSAR spec.



Informal text / UML diagrams / C headers

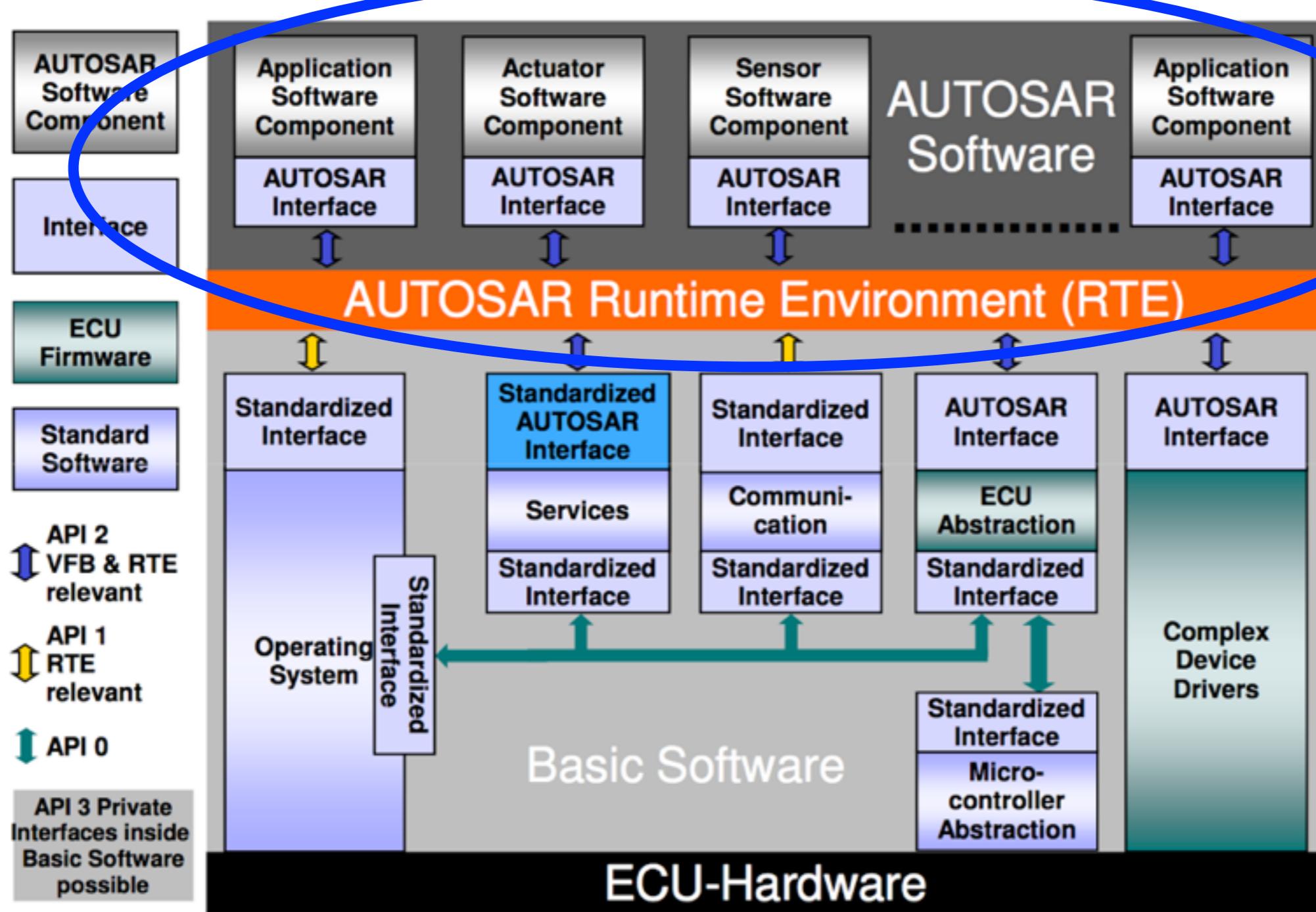
Mixed with (assumed) implementation details

>100 documents!

>12 500 pages!

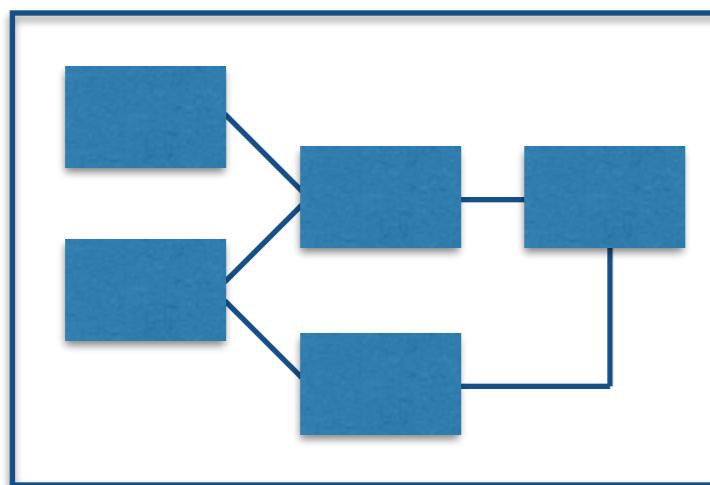
Software Components

>1 600 pages



AUTOSAR development

AUTOSAR Model



Implementation



Manual steps

- Structure & constraints
- Platform independent
- Lacks code
- Not executable

- C files & config tables
- Platform dependent
- Only code
- Executable

Consequences

Can't test an AUTOSAR model

- until after all implementation steps
 - unless all subsystems are present
 - without committing to a particular tool/platform

Can't simulate a model "in the abstract"

Can't really talk about **black box** AUTOSAR behaviour

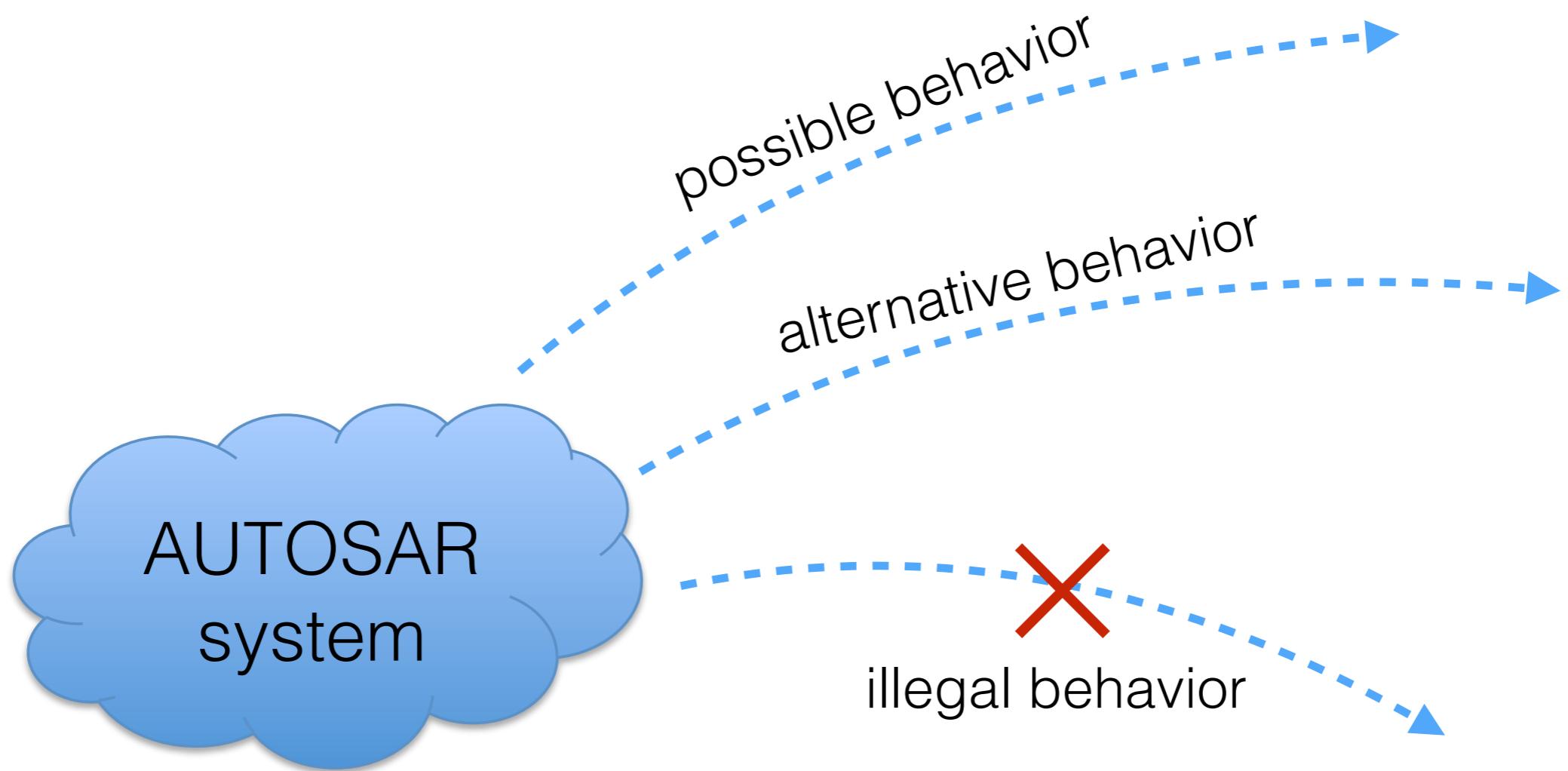
RAWFP @ Chalmers

Resource-aware functional programming
(Exploring Domain-Specific Languages in Haskell)

Theme:
semantics-based analysis, testing & verification in Haskell;
efficient execution after compilation to preferred target code

Validator track 1:
AUTOSAR Software Components as a Haskell DSL
(structure + constraints + code)

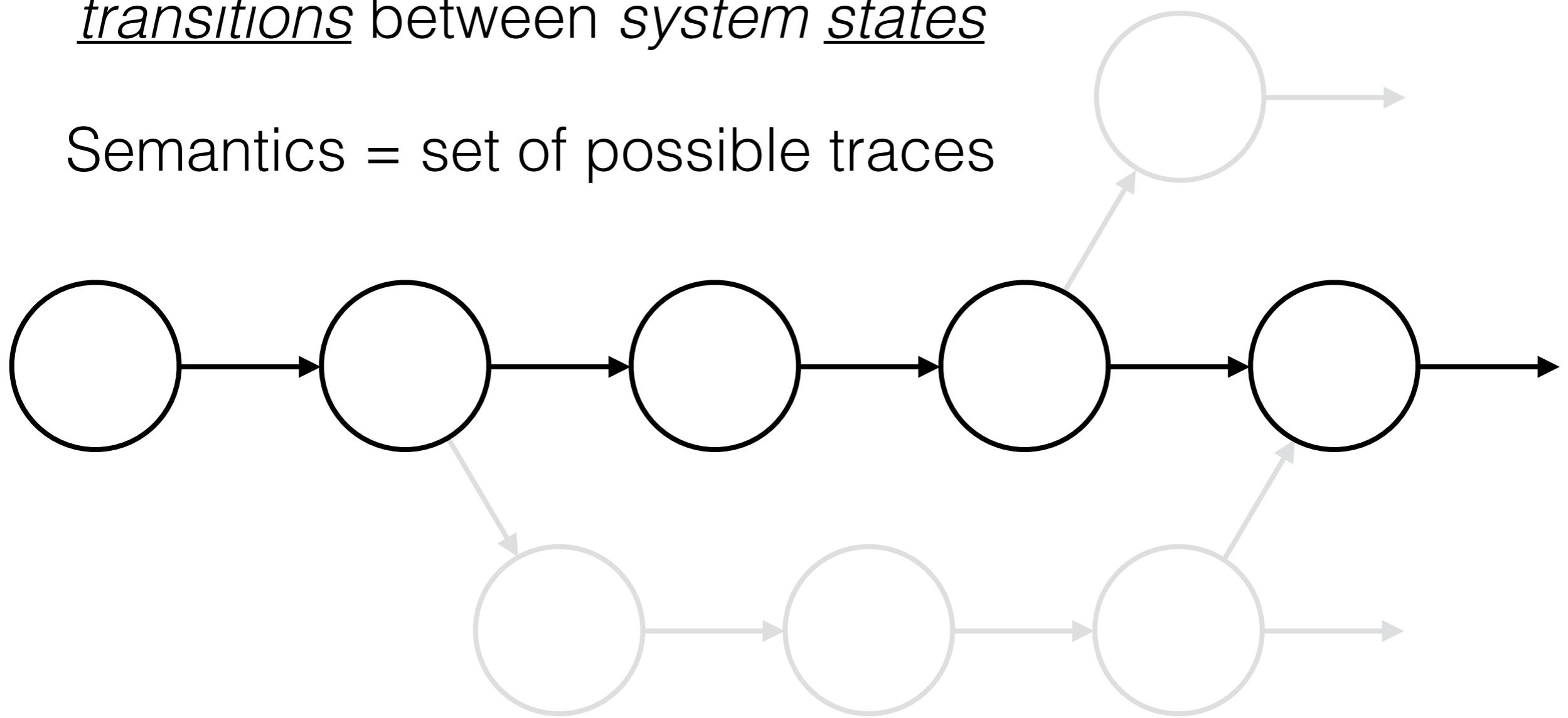
AUTOSAR semantics



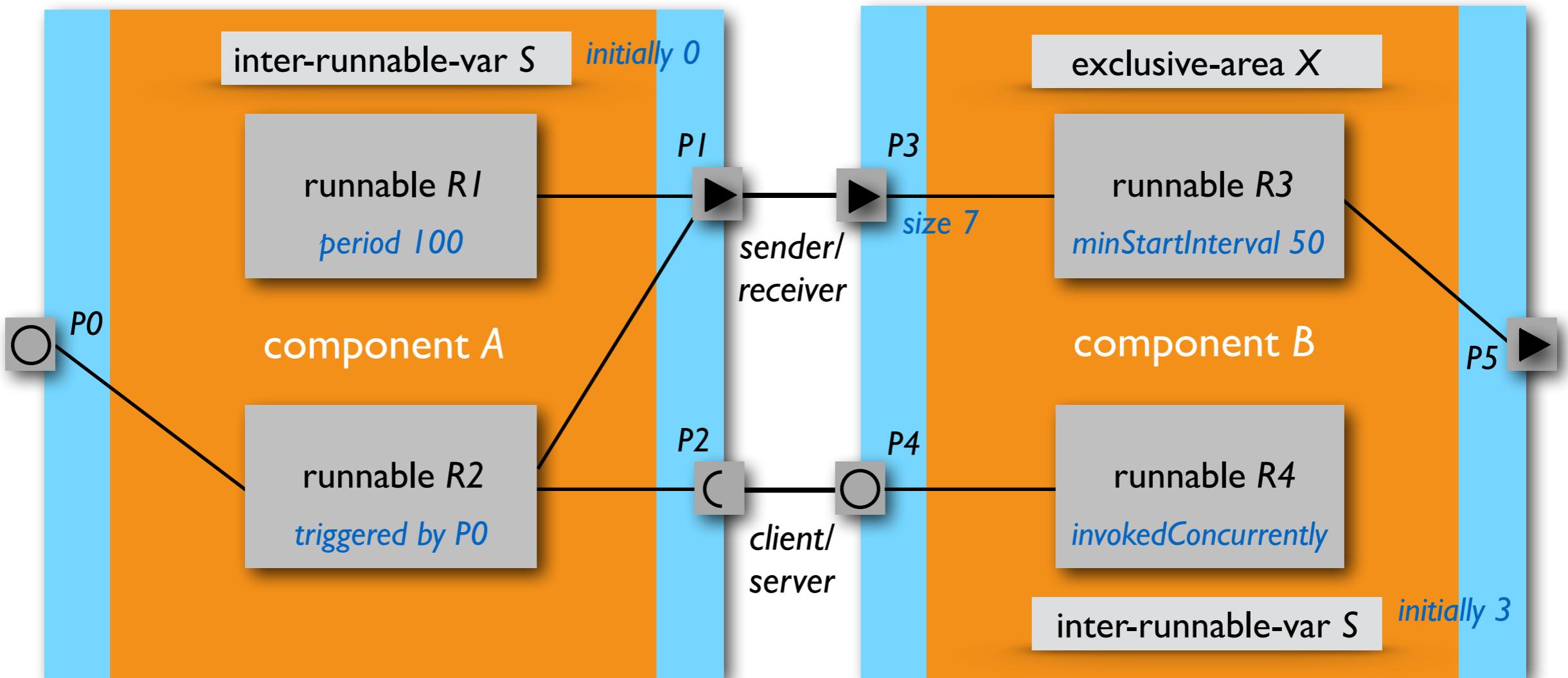
Behaviors

Behavior = trace = sequence of
transitions between system *states*

Semantics = set of possible traces



An AUTOSAR system



+ constraints and annotations

An AUTOSAR system

parallel composition

atomic processes

facts

inter-runnable-var($S:A, \dots$)

exclusive-area($X:B, \dots$)

runnable($R1:A, \dots$)

qelem($P3:B, \dots$)

runnable($R3:B, \dots$)

$rinst(R1:A, \dots)$

$rinst(R1:A, \dots)$

$rinst(R3:B, \dots)$

runnable($R2:A, \dots$)

opres($P2:A, \dots$)

runnable($R4:B, \dots$)

inter-runnable-var($S:B, \dots$)

implementation($R1:A$, Code for $R1$)

implementation($R2:A$, Code for $R2$)

implementation($R3:A$, Code for $R3$)

implementation($R4:A$, Code for $R4$)

$P1:A \Rightarrow P3:B$

$P2:A \Rightarrow P4:B$

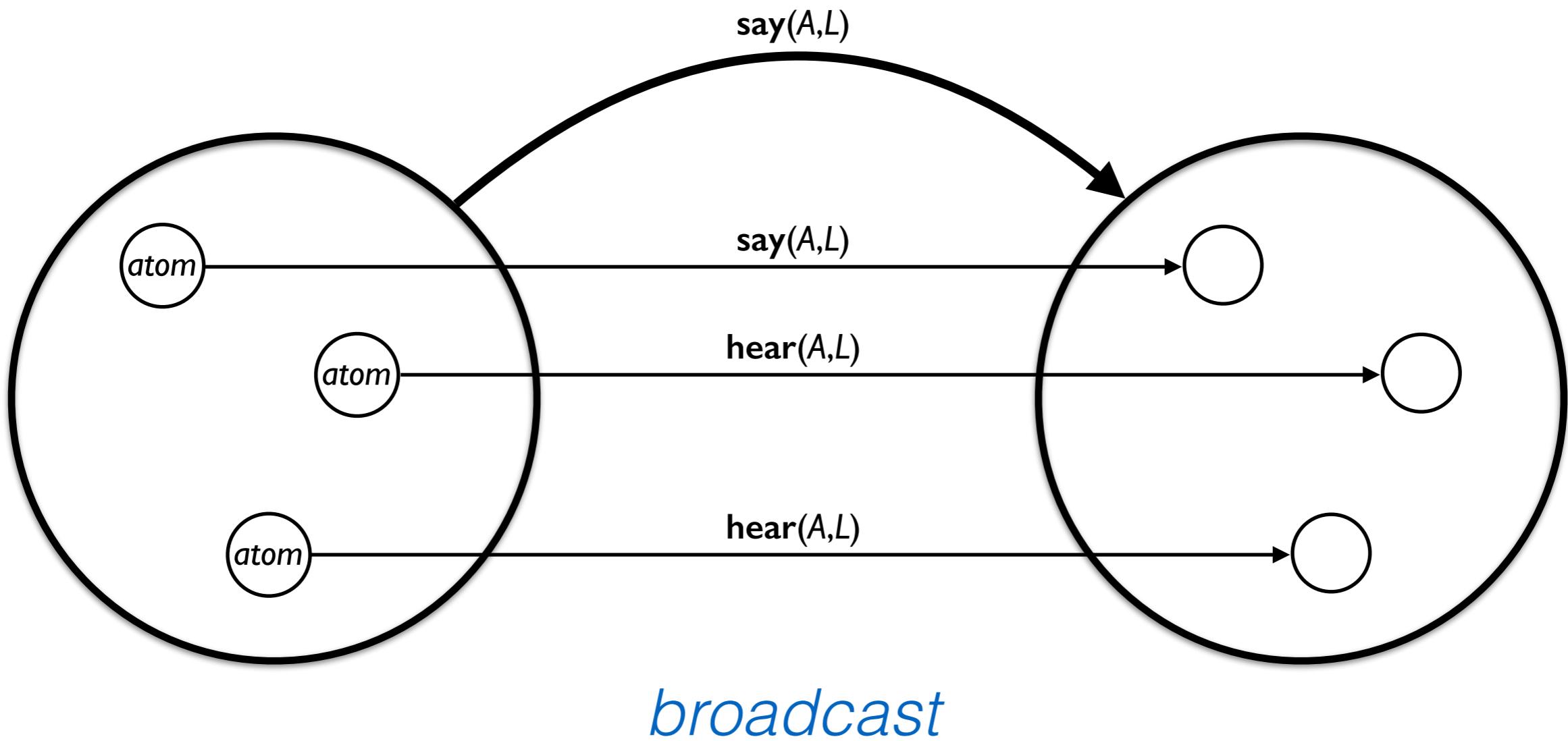
initial($S:A, 0$)

period($R1:A, 100$)

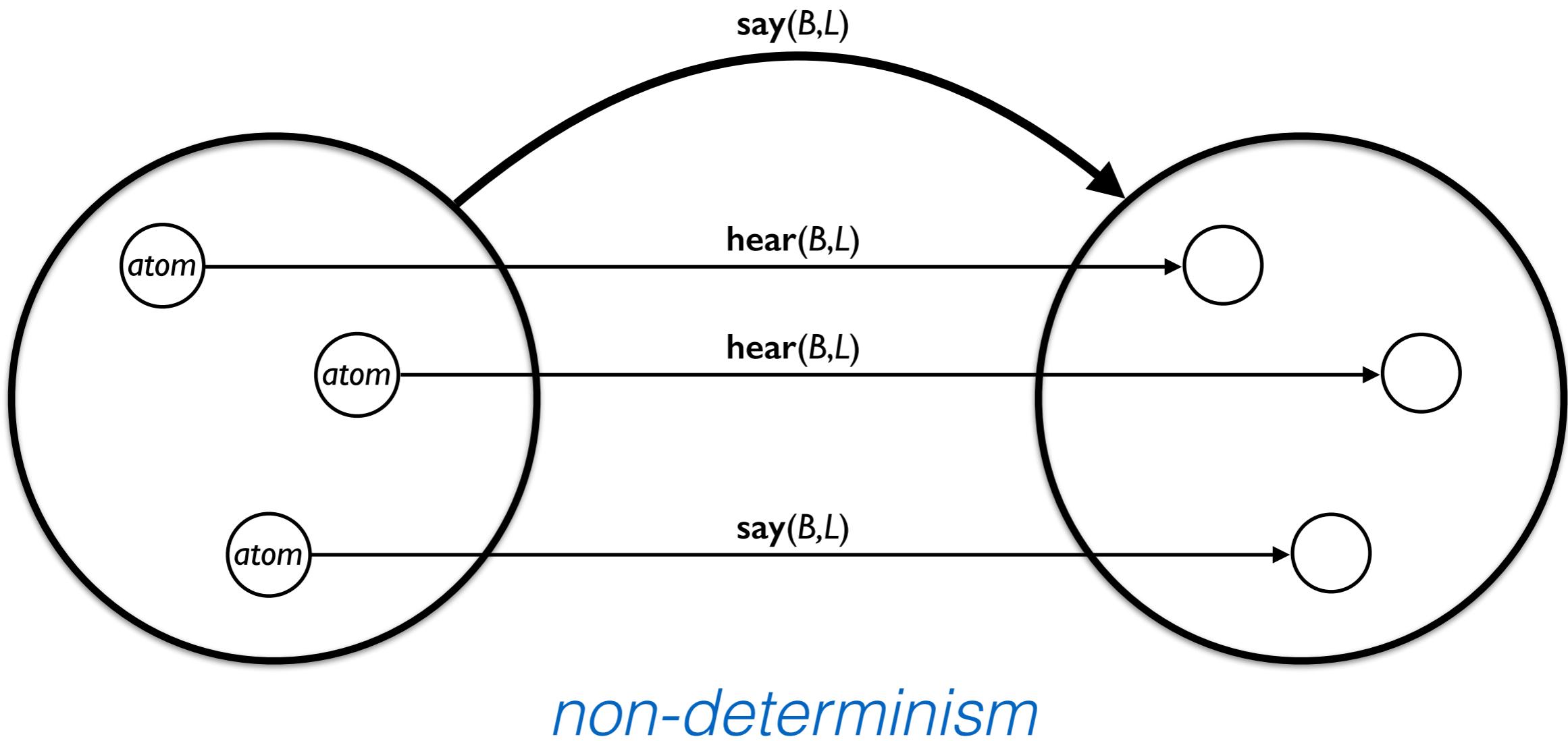
initial($S:B, 3$)

size($P3:B, 7$)

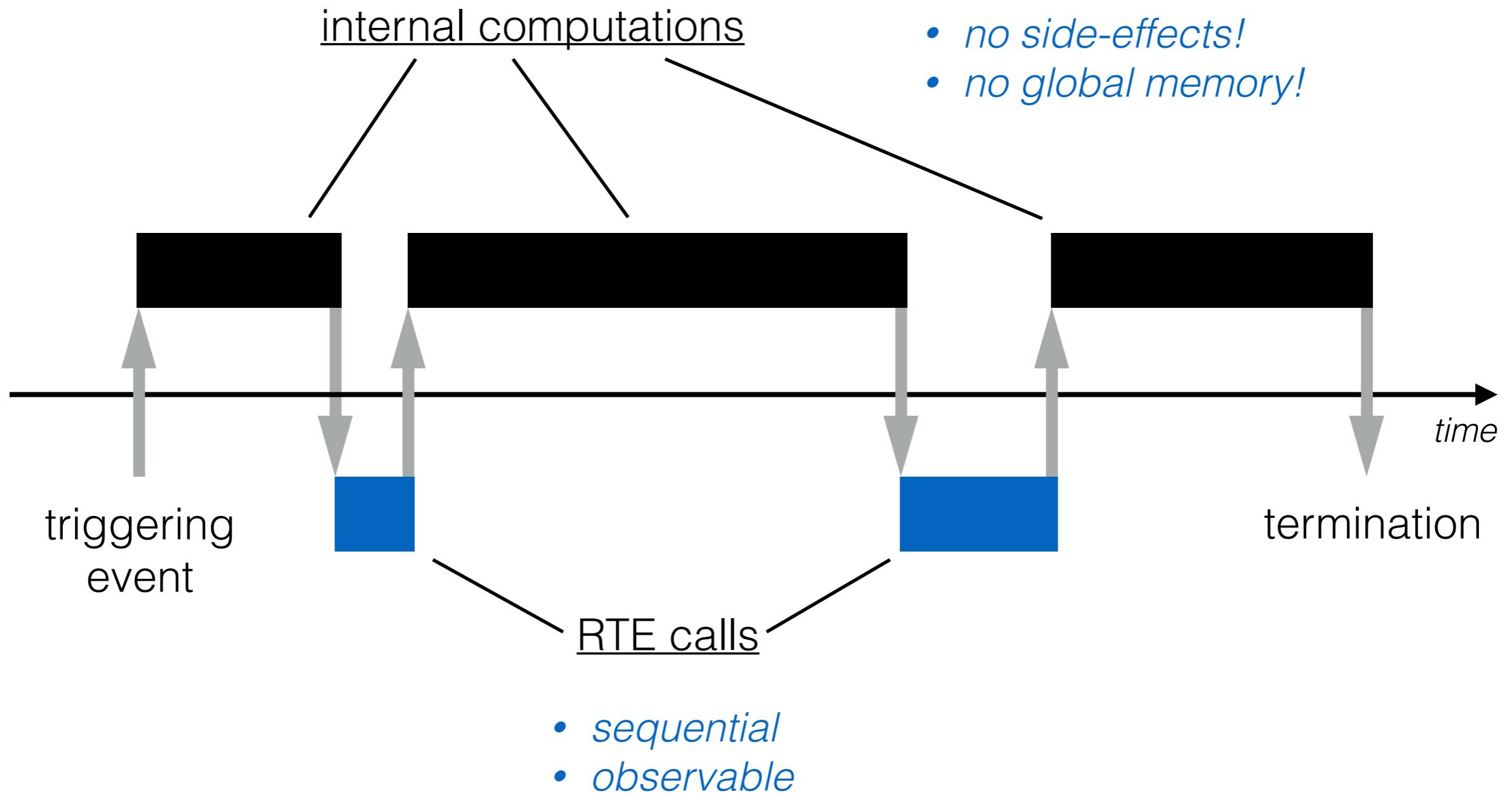
Labelled transitions



Labelled transitions



The timeline of a runnable instance



The Run-Time Environment

rte_send(<i>P, V</i>)	<i>asynchronous send</i>
rte_receive(<i>P</i>)	<i>poll receiver port</i>
rte_call(<i>P, V</i>)	<i>synchronous call</i>
rte_irv_write(<i>S, V</i>)	<i>write shared state</i>
rte_irv_read(<i>S</i>)	<i>read shared state</i>
rte_enter(<i>X</i>)	<i>acquire a lock</i>
rte_exit(<i>X</i>)	<i>release a lock</i>

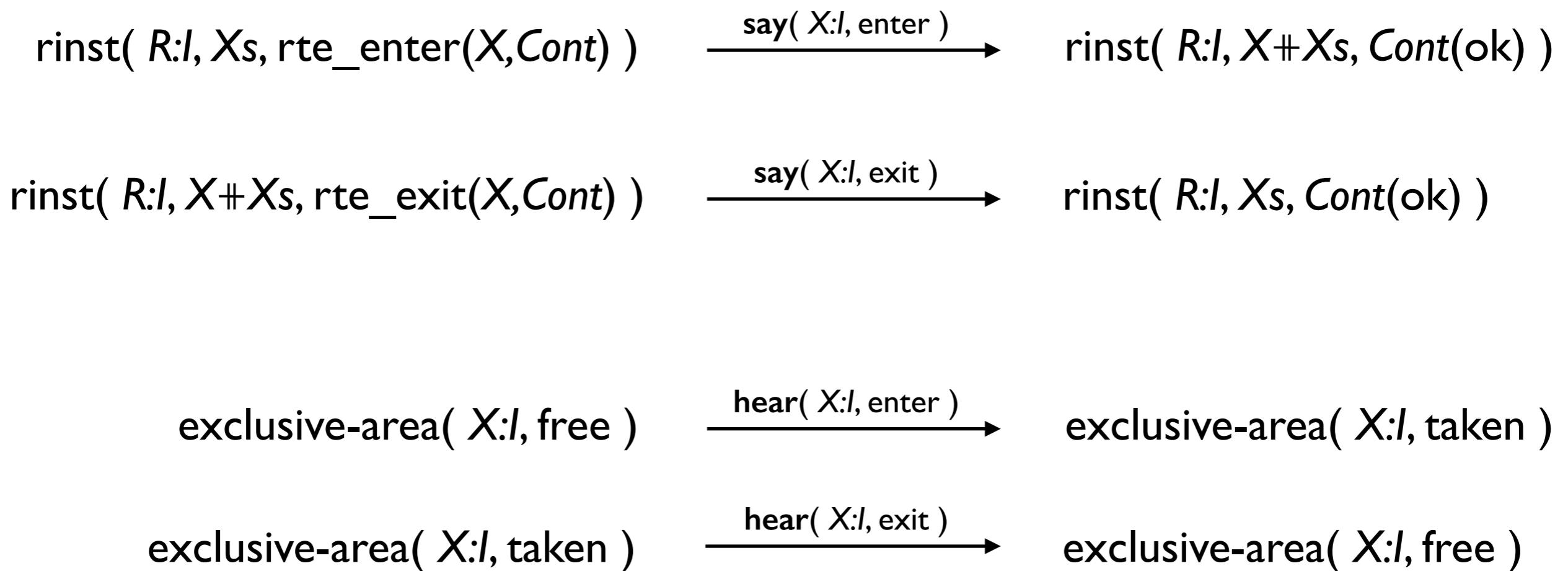
+ a few more

The Run-Time Environment

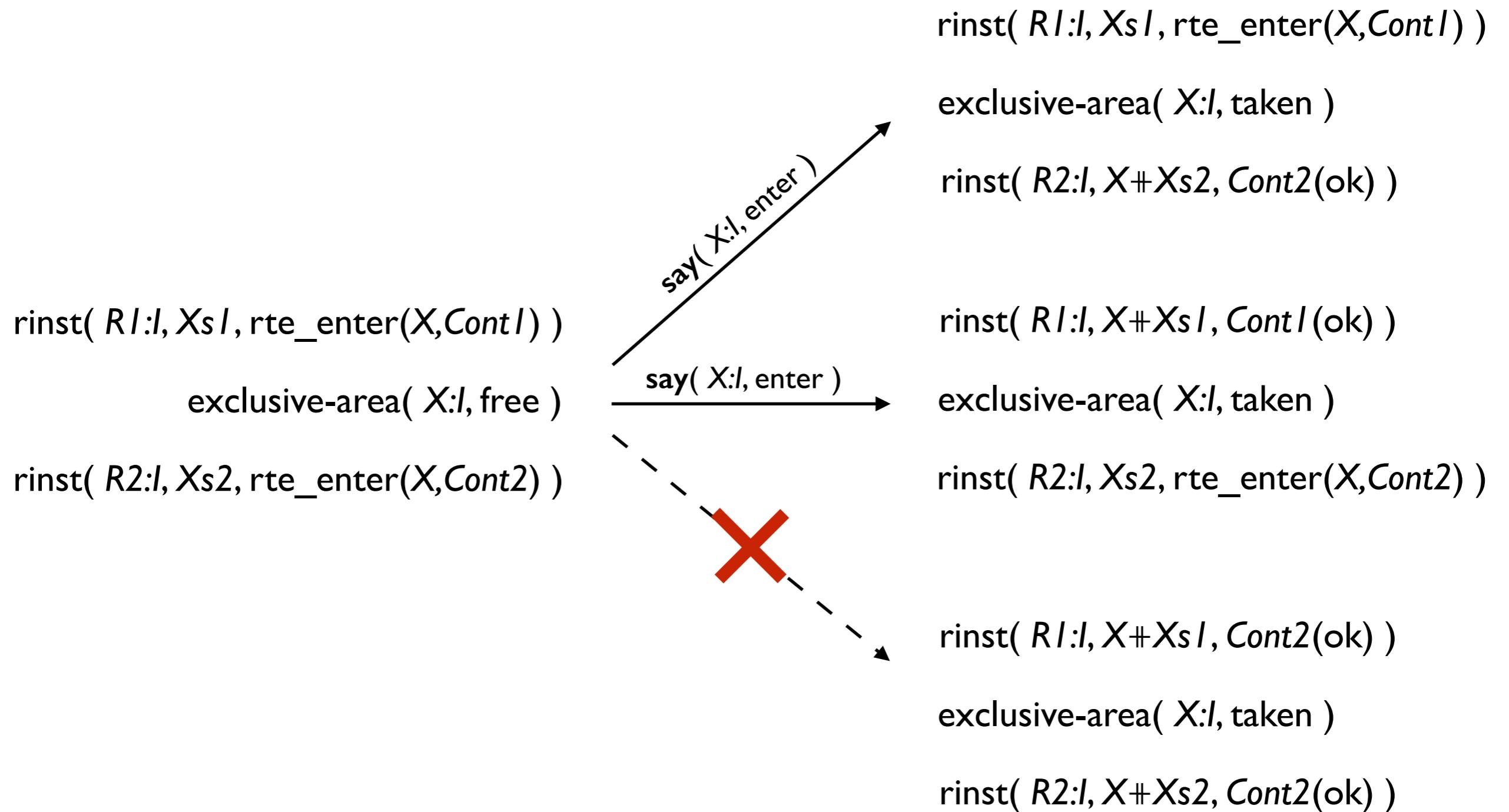
rte_send(<i>P, V, Cont</i>)	<i>asynchronous send</i>
rte_receive(<i>P, Cont</i>)	<i>poll receiver port</i>
rte_call(<i>P, V, Cont</i>)	<i>synchronous call</i>
rte_irv_write(<i>S, V, Cont</i>)	<i>write shared state</i>
rte_irv_read(<i>S, Cont</i>)	<i>read shared state</i>
rte_enter(<i>X, Cont</i>)	<i>acquire a lock</i>
rte_exit(<i>X, Cont</i>)	<i>release a lock</i>
...	
return(<i>V</i>)	<i>terminate</i>

Compute next RTE call: *Cont(V)*

Some simple transitions



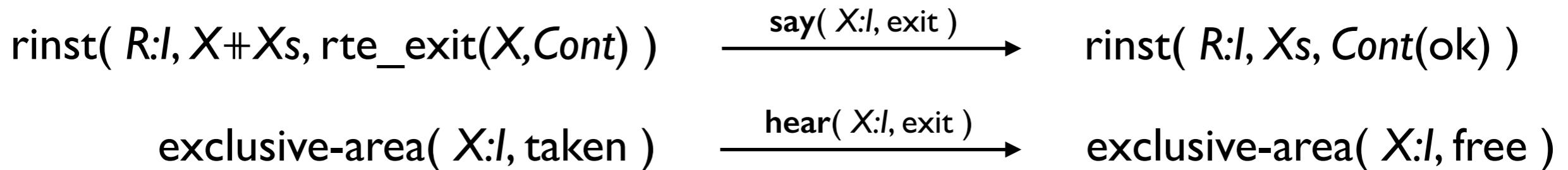
Resulting behaviors



Ambiguities

"The RTE is not required to support nested invocations of rte_exit for the same exclusive area." [Is it allowed?]

"Requirement [SWS_Rte_01122] permits calls to rte_enter and rte_exit to be nested as long as different exclusive areas are exited in the reverse order they were entered." [What if they aren't?]



[Interestingly, deadlock isn't mentioned in the spec.]

Spawning instances

if $A \Rightarrow P:I$, events($R:I$, dataReceived(P)) :

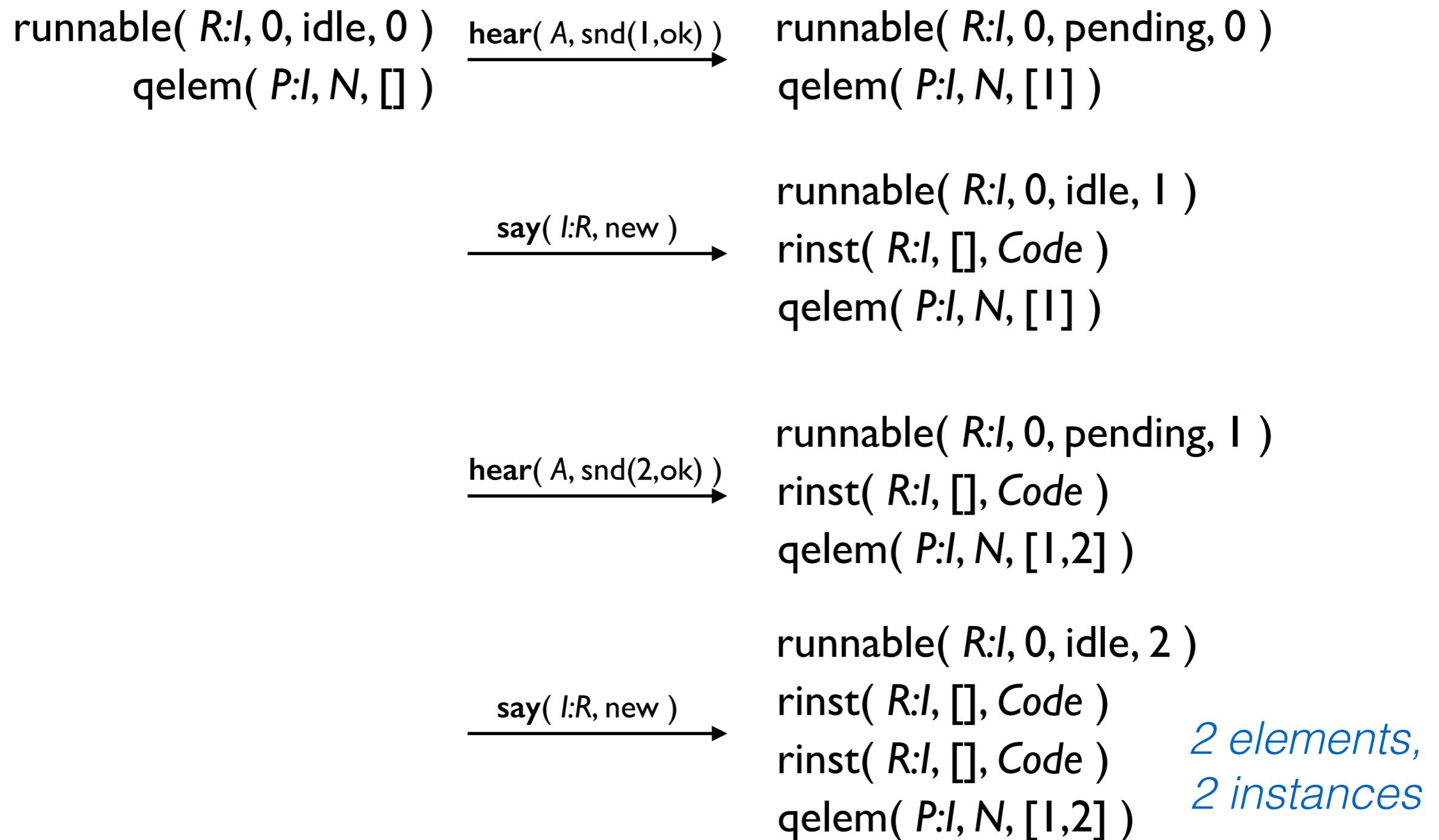
$\text{Runnable}(R:I, T, _, N) \xrightarrow{\text{hear}(A, \text{snd}(_, _))} \text{Runnable}(R:I, T, \text{pending}, N)$

if $N=0 \mid \text{canBeInvokedConcurrently}(R:I)$:

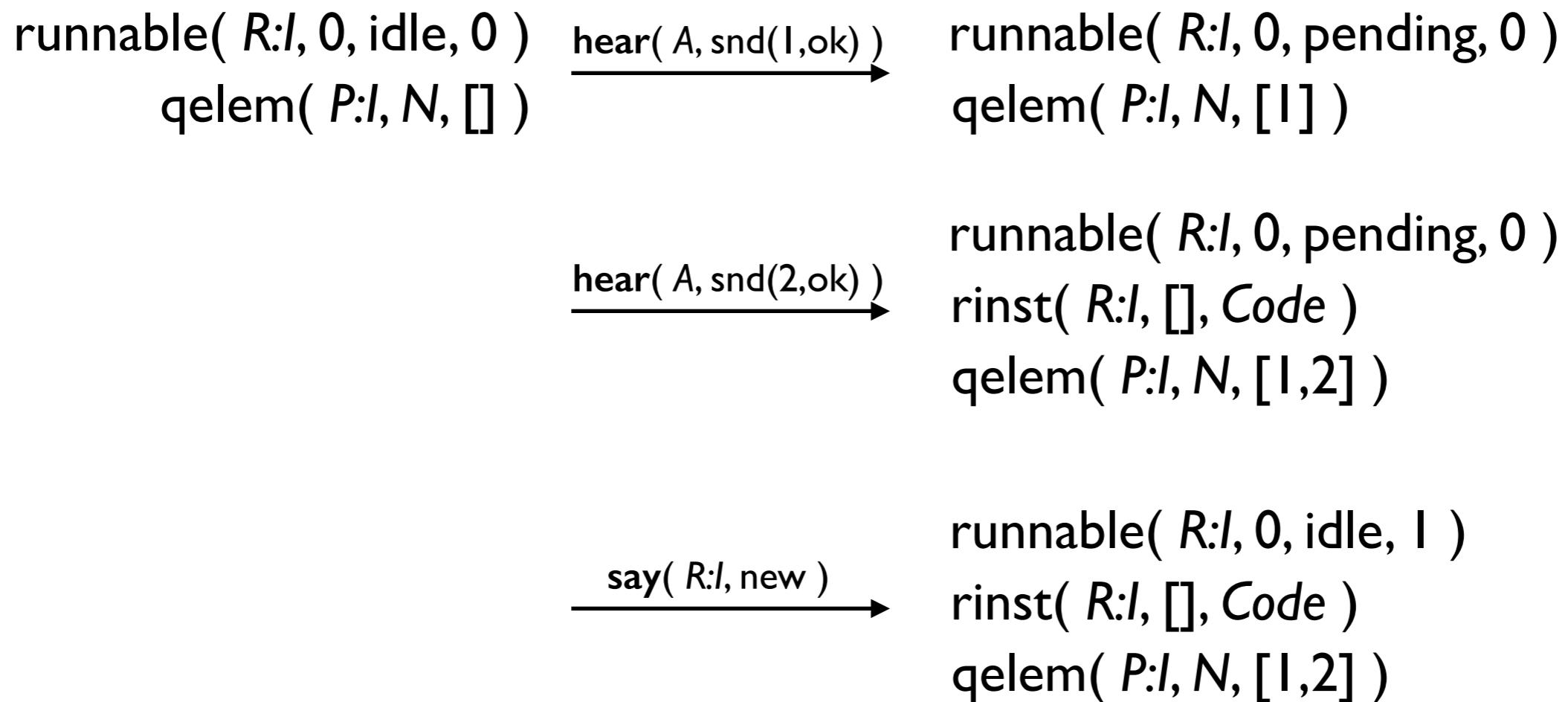
$\text{Runnable}(R:I, 0, \text{pending}, N) \xrightarrow{\text{say}(R:I, \text{new})} \begin{array}{l} \text{Runnable}(R:I, T, \text{idle}, N+1) \\ \text{rinst}(R:I, [], \text{Code}) \\ \left(\begin{array}{l} \text{if } \text{minimumStartInterval}(R:I, T), \\ \text{implementation}(R:I, \text{Code}) \end{array} \right) \end{array}$

one bit of info

A semantic pitfall



A semantic pitfall

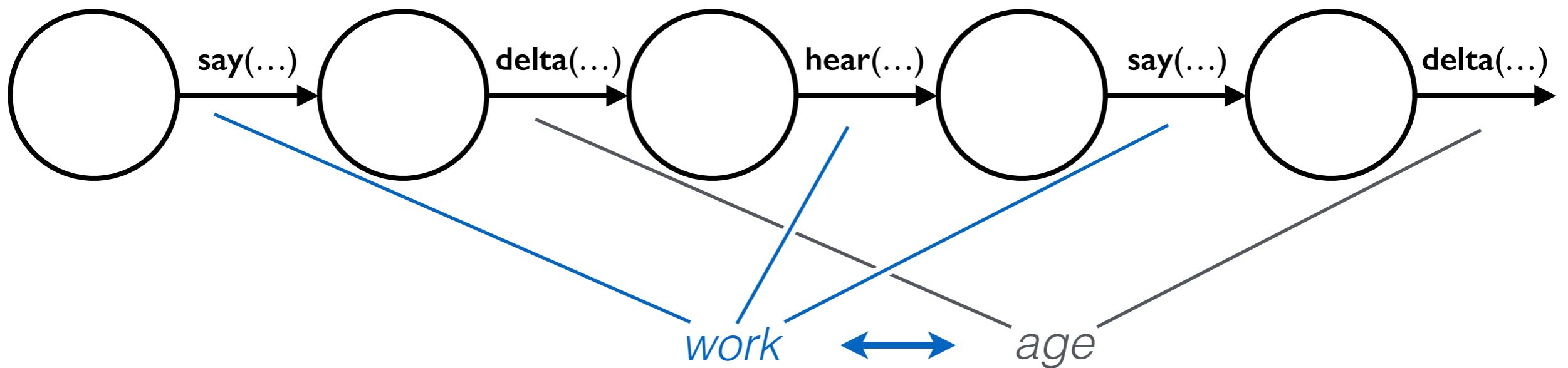


*2 elements,
only 1 instance!*

Passing time

if $V \leq T$:

$$\text{runnable}(R:I, T, \text{Act}, N) \xrightarrow{\text{delta}(V)} \text{runnable}(R:I, T-V, \text{Act}, N)$$



relationship not restricted (arbitrarily fast platform)

Prolog formulation

```
rinst(R:I, Xs, rte_receive(P,Cont)) ---say(P:I,rcv(V))---> rinst(R:I, Xs, Cont(V))
                                                                :  
                                                                :- eval(ap(Cont,V),Code).
```

Negation and arithmetics... careful ordering of predicates!

Good for exhaustive searches of single (few) transitions

A good format for communicating semantic detail?

Not for simulating systems — for this we turn to...

AUTOSAR DSL in Haskell

Embedding Haskell computations inside AUTOSAR

Embedding AUTOSAR simulations inside Haskell

instance	Monad (RTE c)	-- a monad of RTE operations
enter	:: ExclusiveArea c -> RTE c (StdRet ())	
exit	:: ExclusiveArea c -> RTE c (StdRet ())	
irvWrite	:: Data a => InterRunnableVariable a c -> a -> RTE c (StdRet ())	
irvRead	:: Data a => InterRunnableVariable a c -> RTE c (StdRet a)	
send	:: Data a => ProvidedQueueElement a c -> a -> RTE c (StdRet ())	
receive	:: Data a => RequiredDataElement a c -> RTE c (StdRet a)	
write	:: Data a => ProvidedDataElement a c -> a -> RTE c (StdRet ())	
read	:: Data a => RequiredDataElement a c -> RTE c (StdRet a)	
isUpdated	:: RequiredDataElement a c -> RTE c (StdRet Bool)	
invalidate	:: ProvidedDataElement a c -> RTE c (StdRet ())	
call	:: (Data a, Data b) => RequiredOperation a b c -> a -> RTE c (StdRet b)	

AUTOSAR DSL in Haskell

instance Monad (AR c) -- a monad of **structural building blocks**

requiredDataElement :: AR c (RequiredDataElement a c)

providedDataElement :: AR c (ProvidedDataElement a c)

requiredQueueElement :: Int -> AR c (RequiredQueueElement a c)

providedQueueElement :: AR c (ProvidedQueueElement a c)

requiredOperation :: AR c (RequiredOperation a b c)

providedOperation :: AR c (ProvidedOperation a b c)

interRunnableVariable :: Data a => a -> AR c (InterRunnableVariable a c)

exclusiveArea :: AR c (ExclusiveArea c)

runnable :: Invocation -> [Trigger c] -> RTE c a -> AR c ()

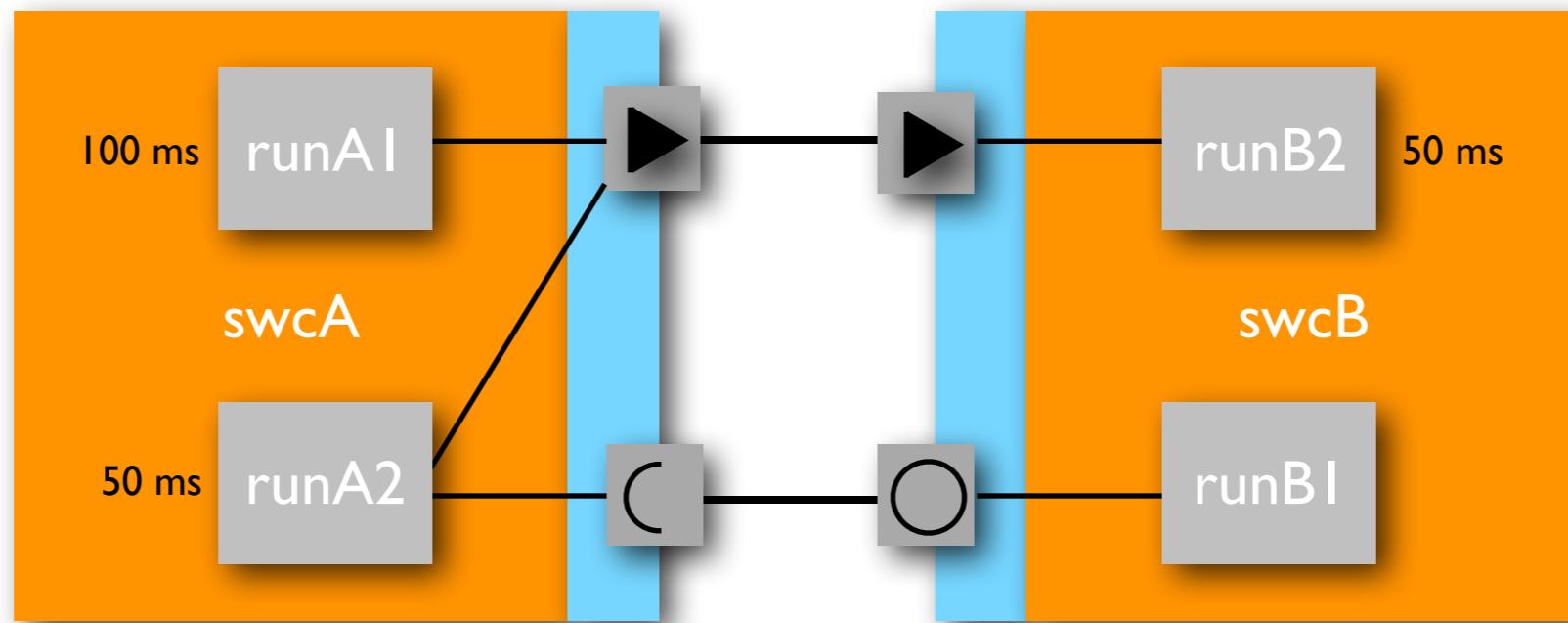
serverRunnable :: (Data a, Data b) =>

Invocation -> [ProvidedOperation a b c] -> (a -> RTE c b) -> AR c ()

component :: (**forall** c . AR c a) -> AR c' a

connect :: Connectable a b => a -> b -> AR c ()

Simple example



Simple example

```
swcA = component $ do
    pport1 <- providedDataElement
    rport1 <- requiredOperation
    runnable (MinInterval 0) [Timed 0.1] (runA1 pport1)
    runnable (MinInterval 0) [Timed 0.05] (runA2 pport1 rport1)
    return (seal pport1, seal rport1)
```

```
swcB = component $ do
    rport2 <- requiredDataElement
    pport2 <- providedOperation
    serverRunnable Concurrent [pport2] runB1
    runnable (MinInterval 0) [Timed 0.05] (runB2 rport2)
    return (seal pport2, seal rport2)
```

```
root = do
    (pdata,rop) <- swcA
    (pop,rdata) <- swcB
    connect pdata rdata
    connect rop pop
```

```
runA1 pport1 = do
    rte_write pport1 val
    ...
runA2 pport1 rport1 = do
    val2 <- rte_call rport1 val1
    ...
    rte_write pport1 val2
runB1 arg = do
    ... arg ...
    return res
```

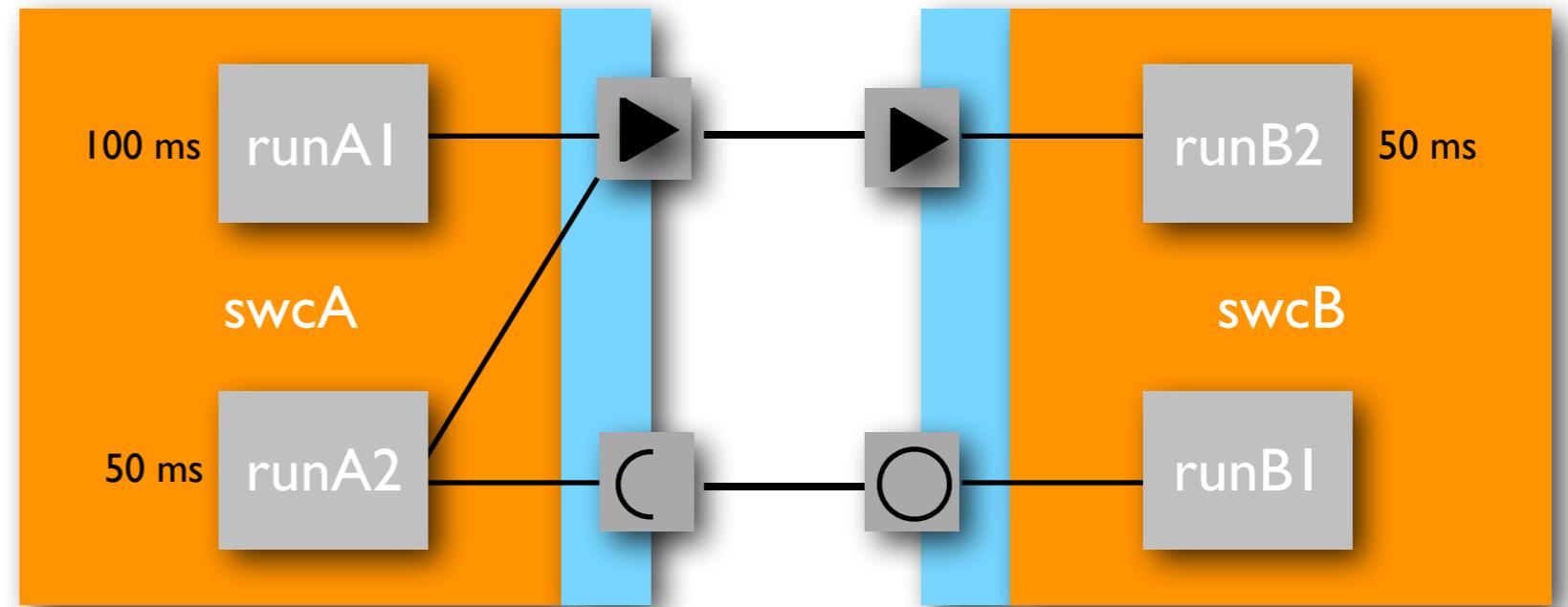
```
runB2 rport2 = do
    val <- rte_read rport2
    ...
```

Simple example (trad)

```
FUNC(void, RTE APPL CODE) runA1(void) {  
    Int16 val;  
    ...  
    Rte_Write_pport1_intValue1(val);  
    ...  
}
```

```
TASK(Task1) {  
    Rte_ReCount_Task1_divby2_0--;  
    if ( Rte_ReCount_Task1_divby2_0 == 0 ) {  
        runA1();  
    }  
    runA2();  
    runB2();  
    if ( Rte_ReCount_Task1_divby2_0 == 0 )  
        Rte_ReCount_Task1_divby2_0 = 2;  
    TerminateTask();  
}
```

```
FUNC(void, RTE APPL CODE) runB2(void) {  
    Int16 val;  
    ...  
    Rte_Read_rport2_intValue(&val);  
    ...  
}
```



```
FUNC(void, RTE APPL CODE) runA2(void) {  
    String8 val1;  
    Int16 val2;  
    ...  
    Rte_Call_rport1_parse(val1, &val2);  
    ...  
    Rte_Write_pport1_intValue1(val2);  
    ...  
}
```

```
FUNC(void, RTE APPL CODE) runB1(String8 arg, Int16 *res) {  
    ... arg ...  
    ...  
    *res = ...  
}
```

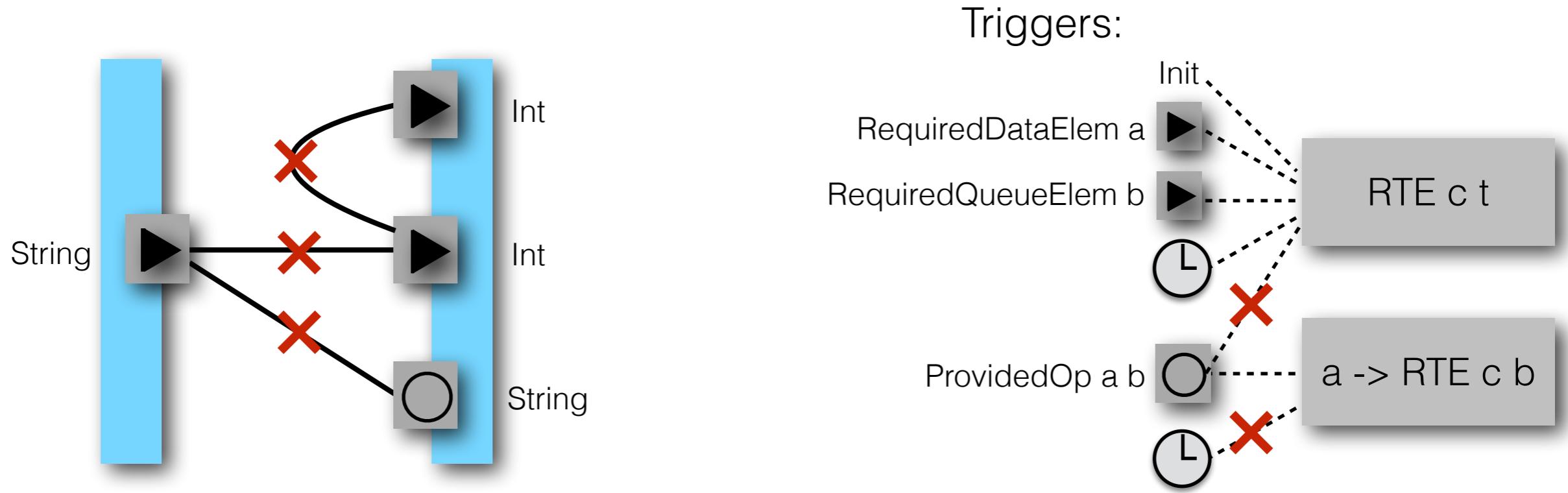
Simple example (trad)

```

<AR-PACKAGE>
  <SHORT-NAME>root</SHORT-NAME>
  <ELEMENTS>
    <ATOMIC-SOFTWARE-COMPONENT-TYPE>
      <SHORT-NAME>swcA</SHORT-NAME>
      <PORTS>
        <P-PORT-PROTOTYPE>
          <SHORT-NAME>pportA1</SHORT-NAME>
          <PROVIDED-INTERFACE-TREF DEST="SENDER-RECEIVER-INTERFACE">
            /interfaces/SR Int16
          </PROVIDED-INTERFACE-TREF>
        </P-PORT-PROTOTYPE>
        <R-PORT-PROTOTYPE>
          <SHORT-NAME>rportA1</SHORT-NAME>
          <REQUIRED-INTERFACE-TREF DEST="CLIENT-SERVER-INTERFACE">
            /interfaces/CS string to int
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        </R-PORT-PROTOTYPE>
      </PORTS>
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    <ATOMIC-SOFTWARE-COMPONENT-TYPE>
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      <PORTS>
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  </IMPLEMENTATION>
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</AR-PACKAGE>

```

Captured by types



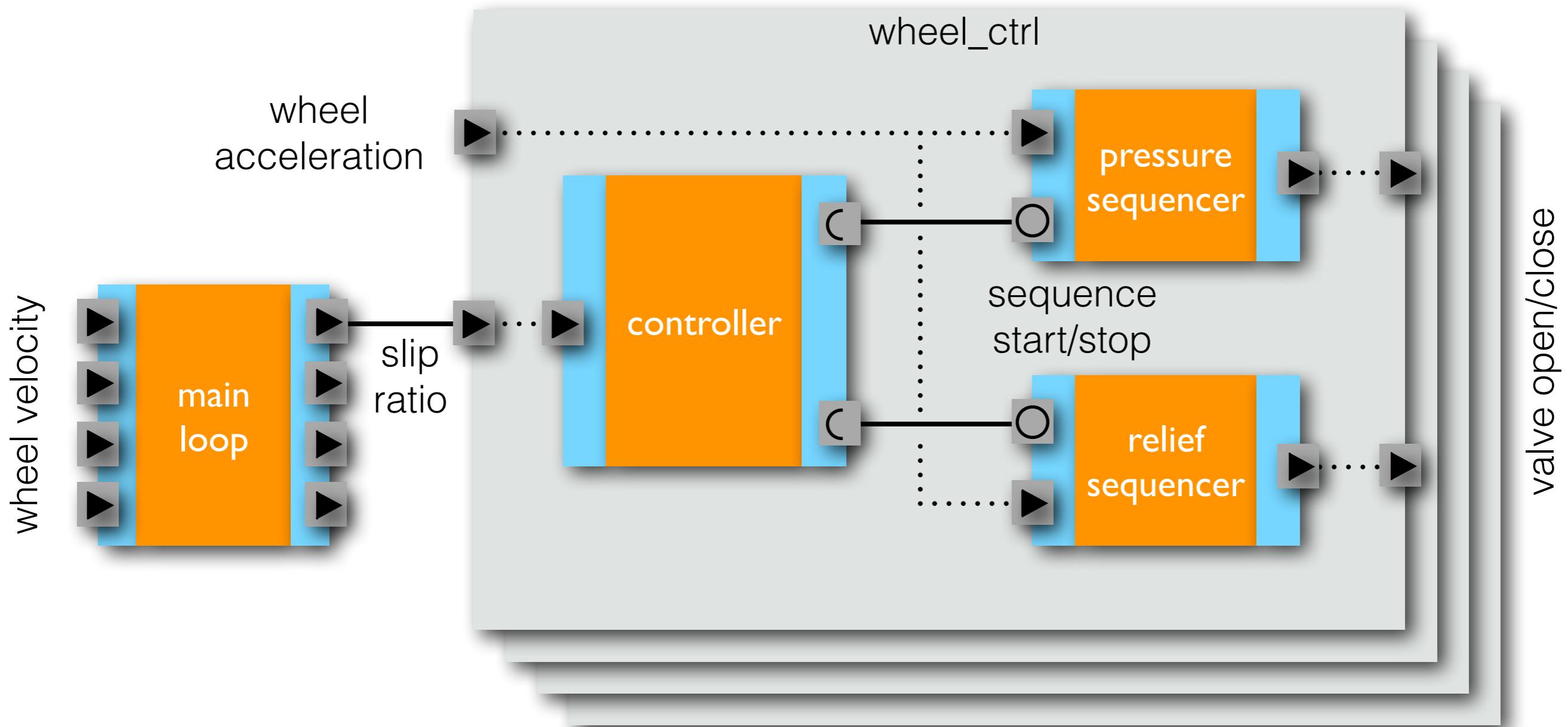
escaped <- component \$ **do**
v <- interRunnableVariable

...
~~return v~~

(the "runST" trick)

method = **do**
x <- irvRead escaped
...

Demo: An ABS system



ABS top level

```
loop velostreams slipstreams = do
    velos <- mapM (\re -> do Ok v <- rteRead re; return v) velostreams
    let v0 = maximum velos
    mapM (\(v,pe) -> rteSend pe (slip v0 v)) (velos `zip` slipstreams)
```

```
main_loop = component $ do
    velostreams <- mapM (const requiredDataElement) [1..4]
    slipstreams <- mapM (const providedQueueElement) [1..4]
    runnable (MinInterval 0) [Timed 0.01] (loop velostreams slipstreams)
    return (map seal velostreams, map seal slipstreams)
```

:: [RequiredDataElement Double c]

:: [RequiredDataElem Double]

```
abs_system = component $ do
    (velos_in, slips_out) <- main_loop
    wheelctrls <- mapM wheel_ctrl ([1..4] `zip` slips_out)
    return (velos_in, wheelctrls)
```

Code

Structure

ABS wheel controller

```
wheel_ctrl (i,slipstream) = component $ do
  (slip, onoff_pressure, onoff_relief) <- controller
  (accel_p, ctrl_p, valve_p) <- pressure_seq
  (accel_r, ctrl_r, valve_r) <- relief_seq
```

Create sub-components

```
connect slipstream slip
connect onoff_pressure ctrl_p
connect onoff_relief ctrl_r
```

Setup the internal wiring

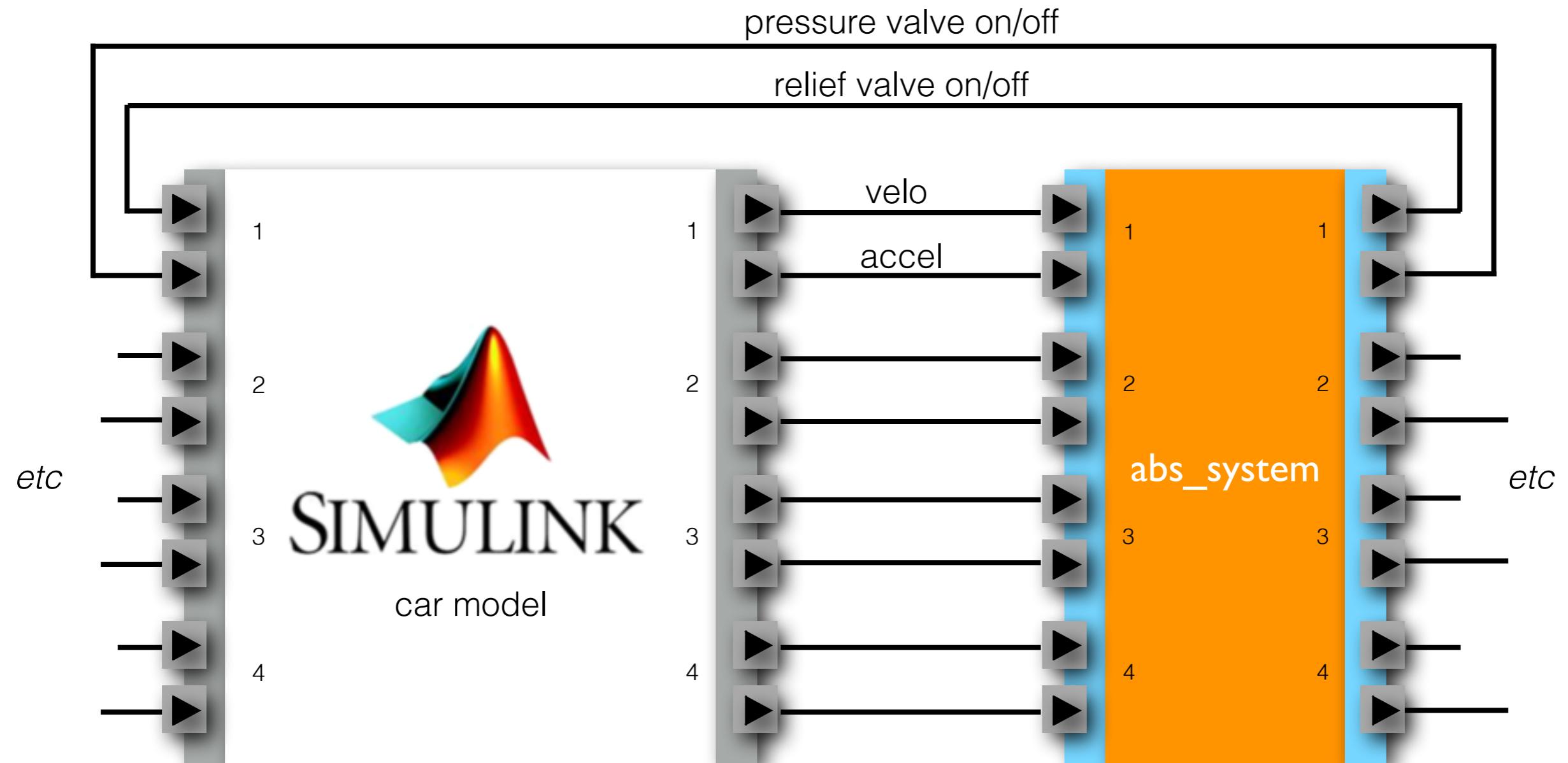
```
when (i==1) $ do
  probeWrite "relief" valve_r ((+2.0) . boolToDouble)
  probeWrite "pressure" valve_p scaleValve_p ((+5.0) . boolToDouble)
```

Attach test probes

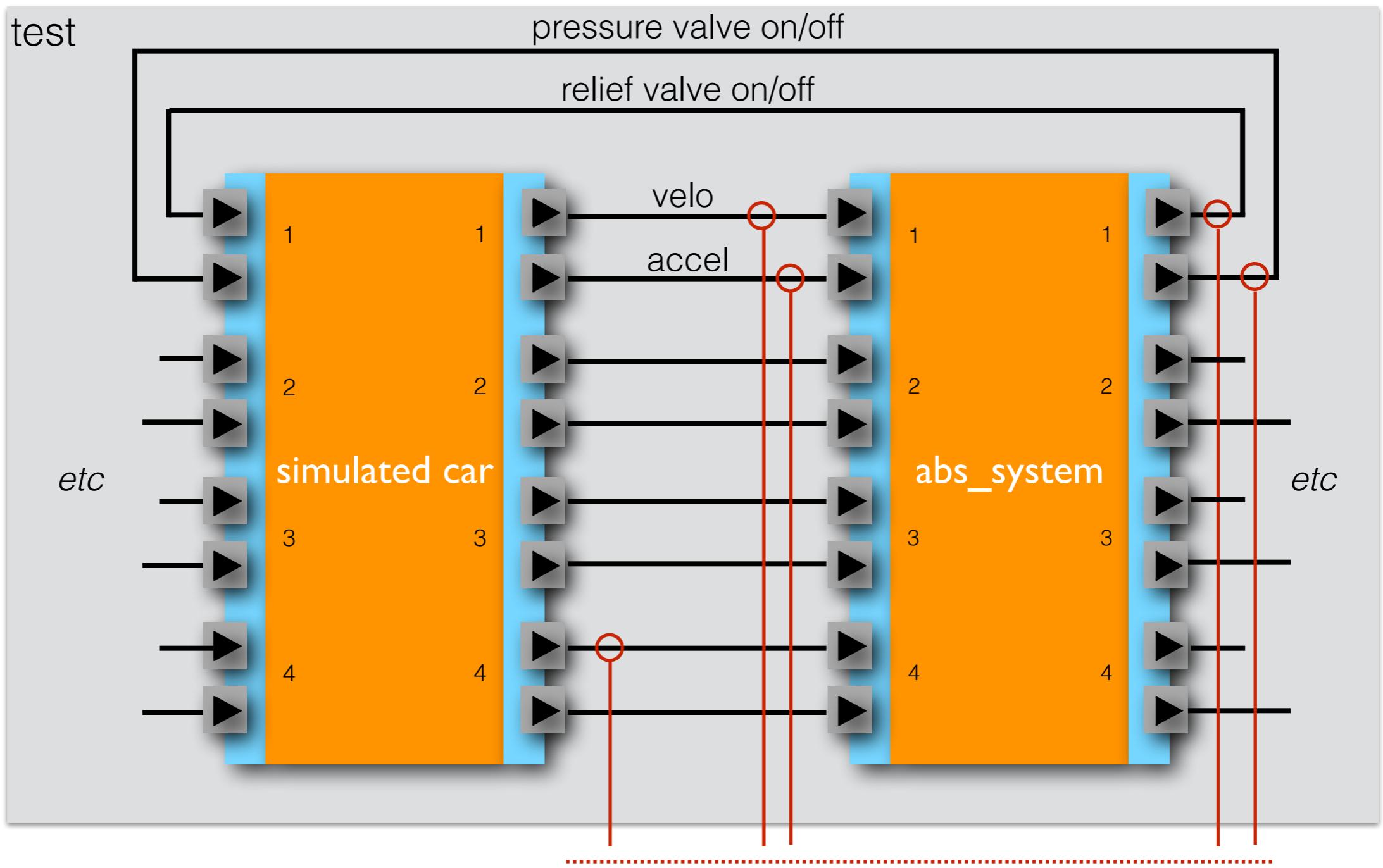
```
return (accel_r, accel_p, valve_r, valve_p)
```

Trivial delegation connectors

Simulation setup



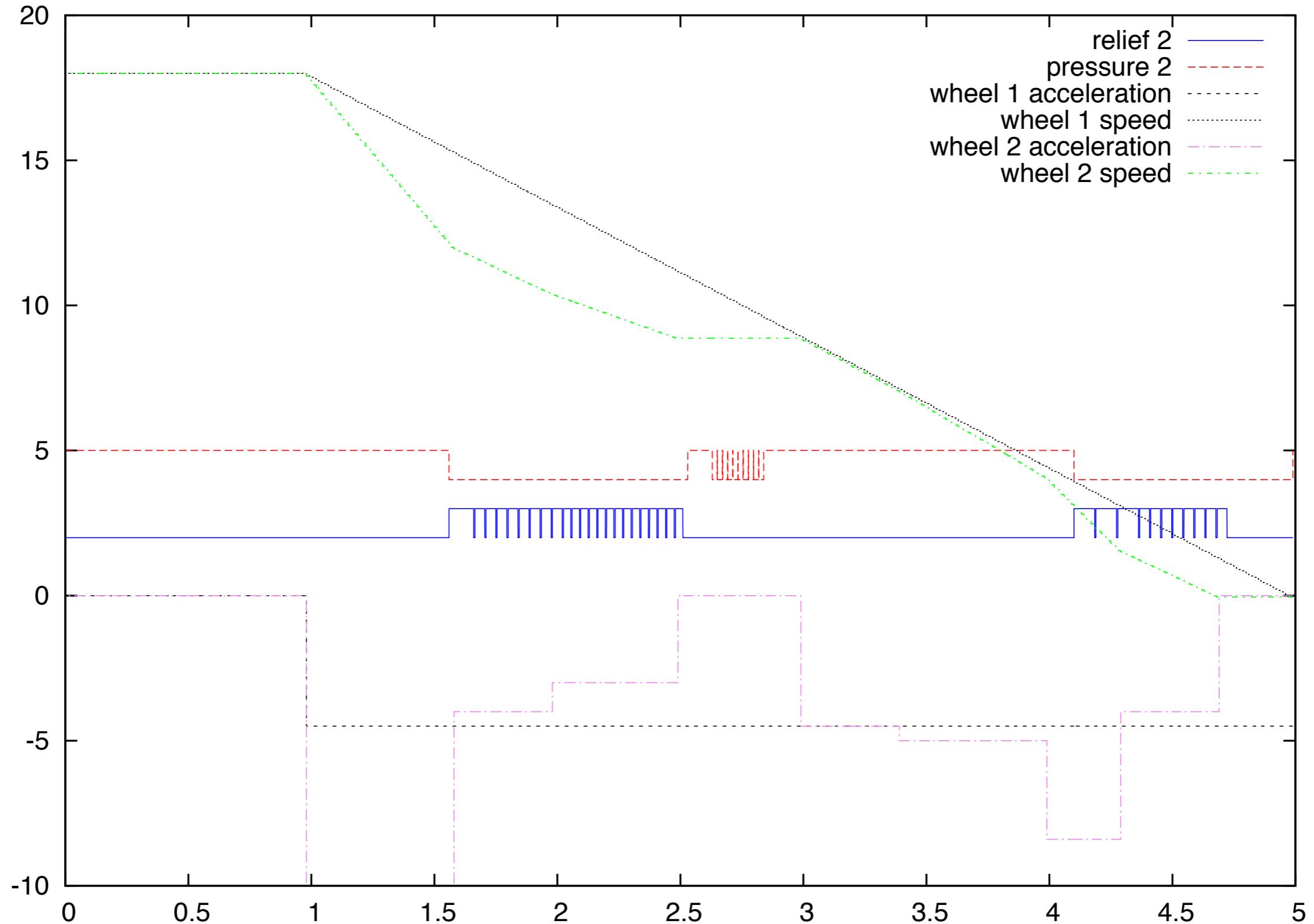
Simulation setup



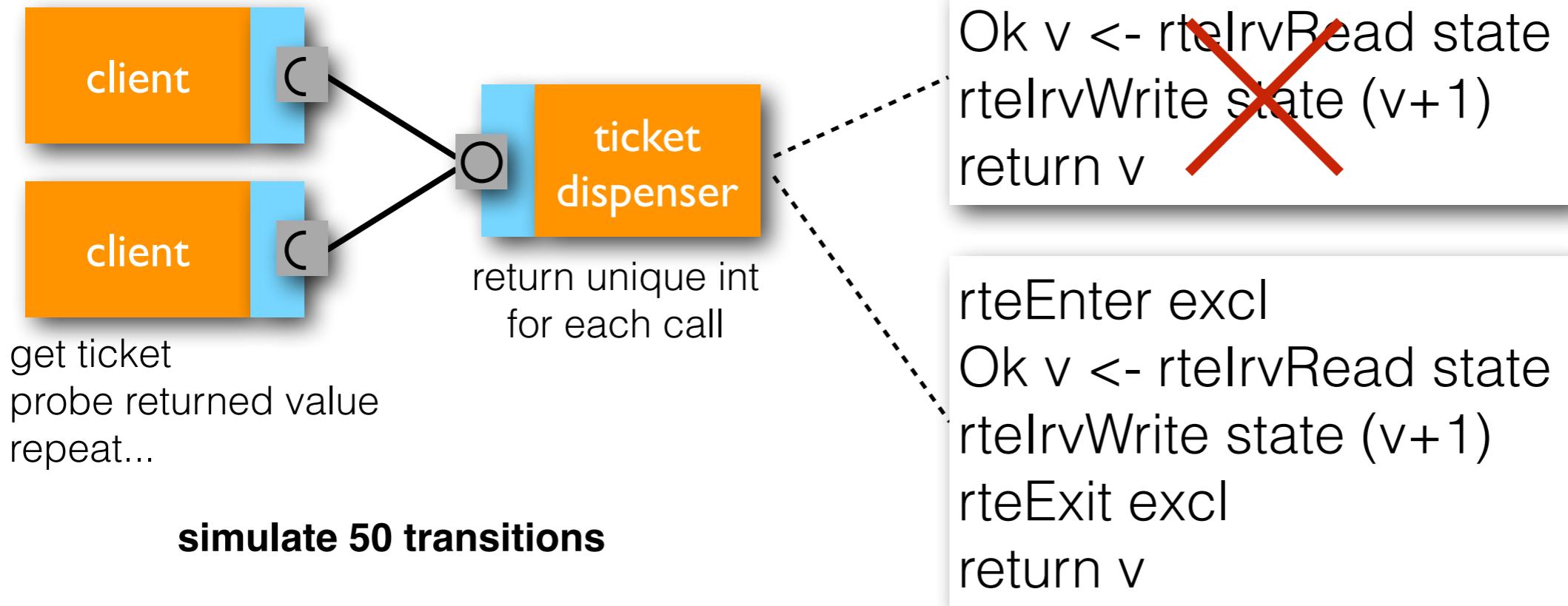
```
main = printLogs trace >> makePlot trace
```

```
where trace = limitTime 5.0 $ execSim (RandomSched (mkStdGen 111)) test
```

Simulation output



Detecting a race condition



With round-robin scheduling:

```
> ./TicketDispenser  
[0,1,2,3,4,5]  
> ./TicketDispenser  
[0,1,2,3,4,5]  
> ./TicketDispenser  
[0,1,2,3,4,5]  
>
```

With random scheduling:

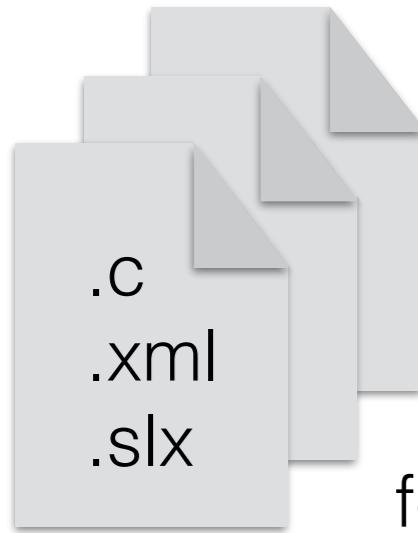
```
> ./TicketDispenser  
[1,0,2,3,4]  
> ./TicketDispenser  
[0,1,2,3,4,3]  
> ./TicketDispenser  
[0,1,2,3,4,5]  
>
```

Corrected:

```
> ./TicketDispenser  
[0,1,2,3,4]  
> ./TicketDispenser  
[0,1,2,3]  
> ./TicketDispenser  
[1,0,2,3]
```

DSL use cases

Manual
construction



```
module ARExample w
import ARSim

compA <- component $ do
  v <- interRunnableVariable
  x <- exclusiveArea
  return (ifc v x)

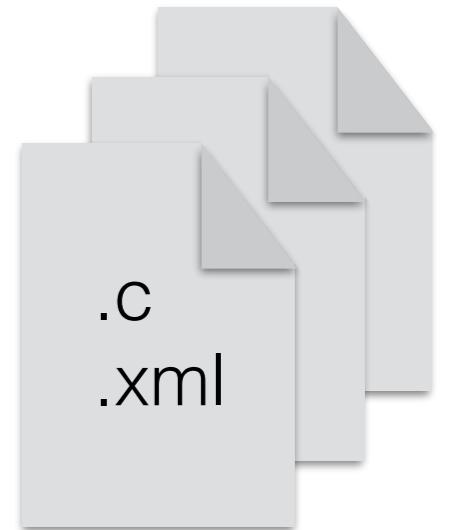
method v = do
  Ok k <- irvRead v
  bla bla

ifc v x = ...
bla bla ...
```

"decompilation"

optimization
refactoring

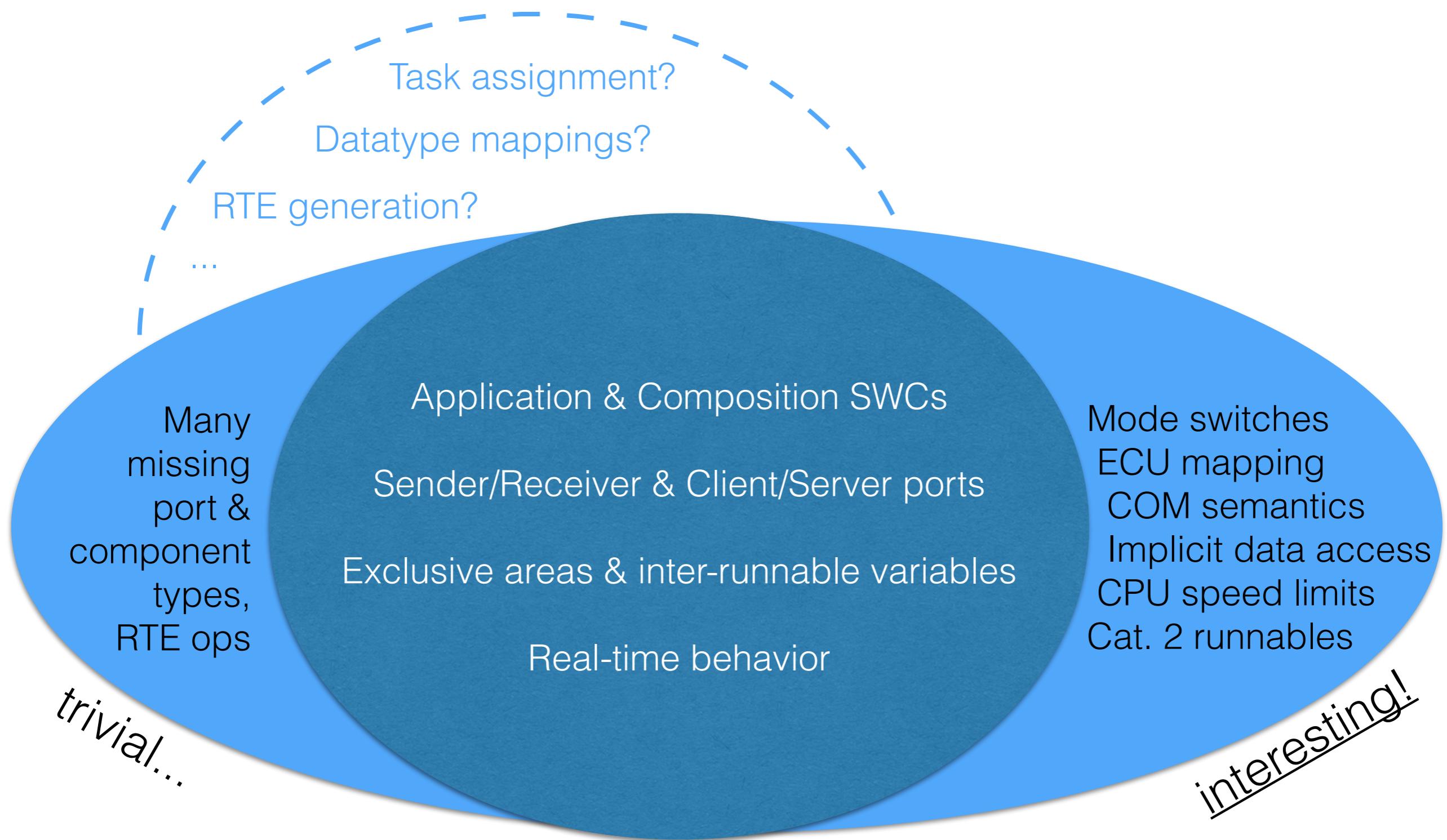
compilation



Simulator
output

feasible subset?

Outlook



Take away bullets

- Platform-independent standard →
platform-independent testing & simulation!
- Concurrent semantics → **random scheduling!**
- Haskell ↔ embedded automotive programming!
(via a DSL and simulation)
- AUTOSAR runnables → strictly controlled side-effects →
a Haskell monad!