

# Purely functional distributed programming

for collaborative applications.



@aidylns



@parenthetical

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Work supported by



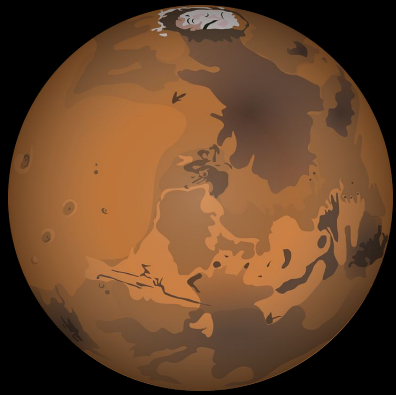
Protocol  
Labs



FACULDADE DE  
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NOVALINCS



*Why is writing this application hard?*



*Not enough functional programming!*

Please ask  
questions!

# ping

```
client(Pid) ->  
  {server, Pid} ! {ping,self()};  
  receive  
    pong ->  
      client(Pid)  
  end.
```

```
server()  
  receive  
    {ping, Pid} ->  
      Pid ! pong;  
      server()  
  end.
```

# ping

```
client(Pid) ->  
  {server, Pid} ! {ping, self()};  
  receive  
    pong ->  
      client(Pid)  
  end.
```

**Can we do better than ickiness?**

impure  
ickiness

```
server()  
  receive  
    {ping, Pid} ->  
      Pid ! pong;  
      server()  
  end.
```

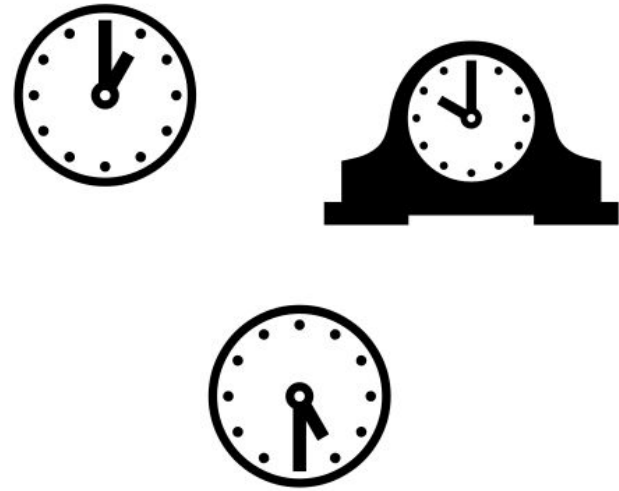
What is a  
distributed  
program?

“places”



Space

“moments”



Time



Spacetime  $\rightarrow a$

temperature ::  
Spacetime → Kelvin

# *Relativistic Functional Reactive Programming*

Behavior  $a$  = Spacetime  $\rightarrow a$

Event  $a$  = Map Spacetime  $a$

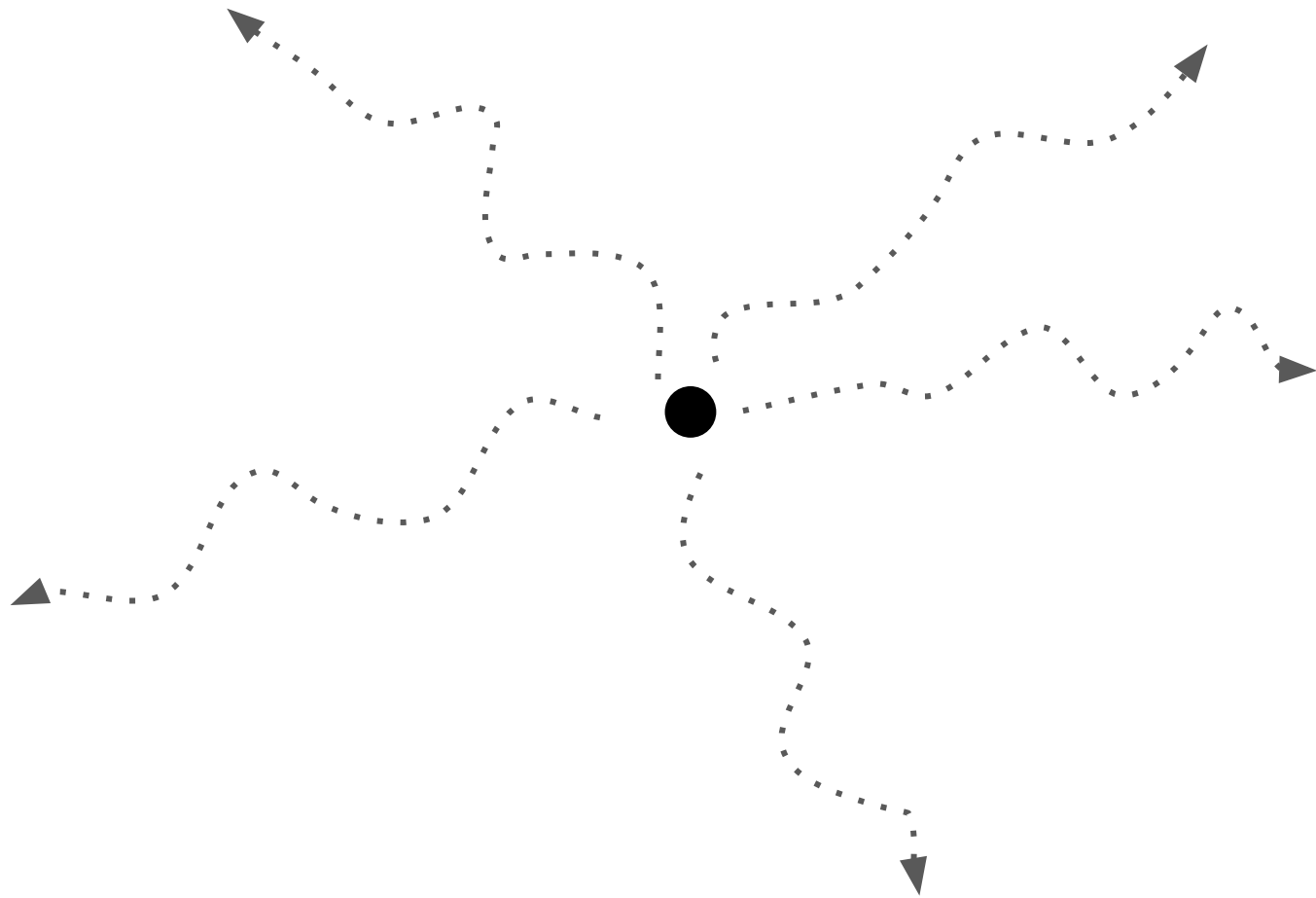
# *Relativistic Functional Reactive Programming*

Conal Elliott & Paul Hudak, 1997

Behavior  $a$  = Spacetime  $\rightarrow a$

Event  $a$  = Map Spacetime  $a$

*What about communication?*

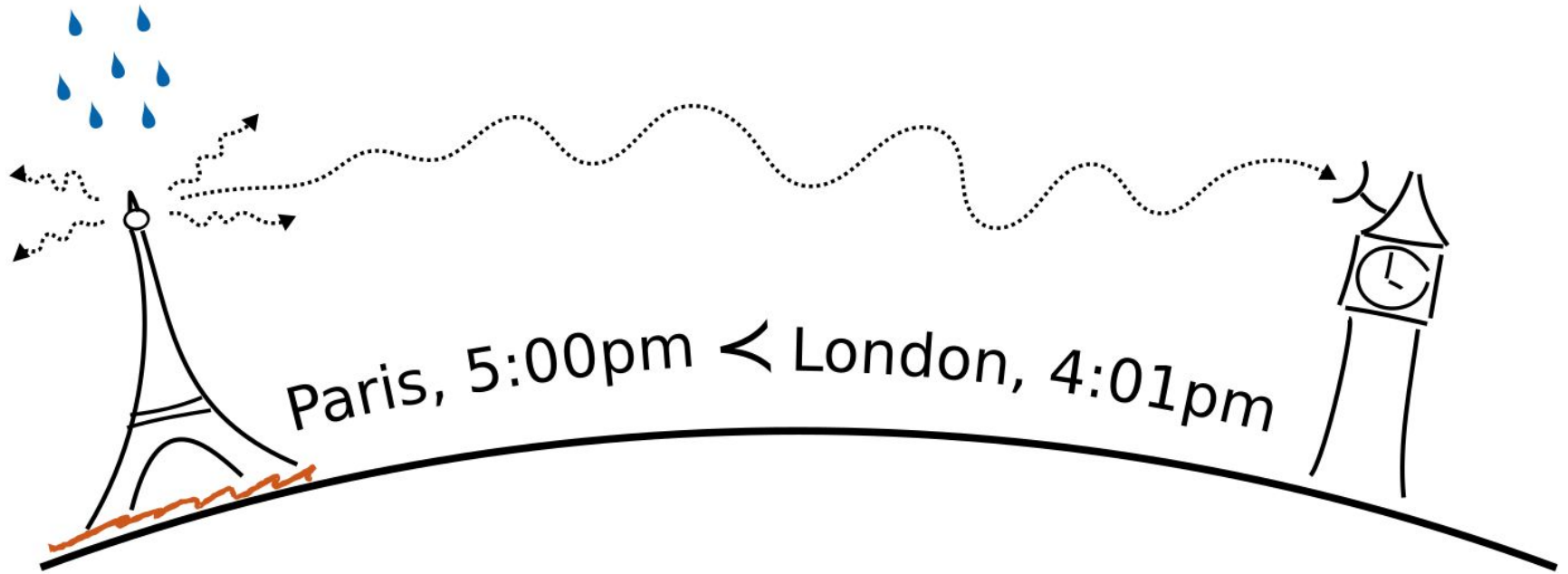




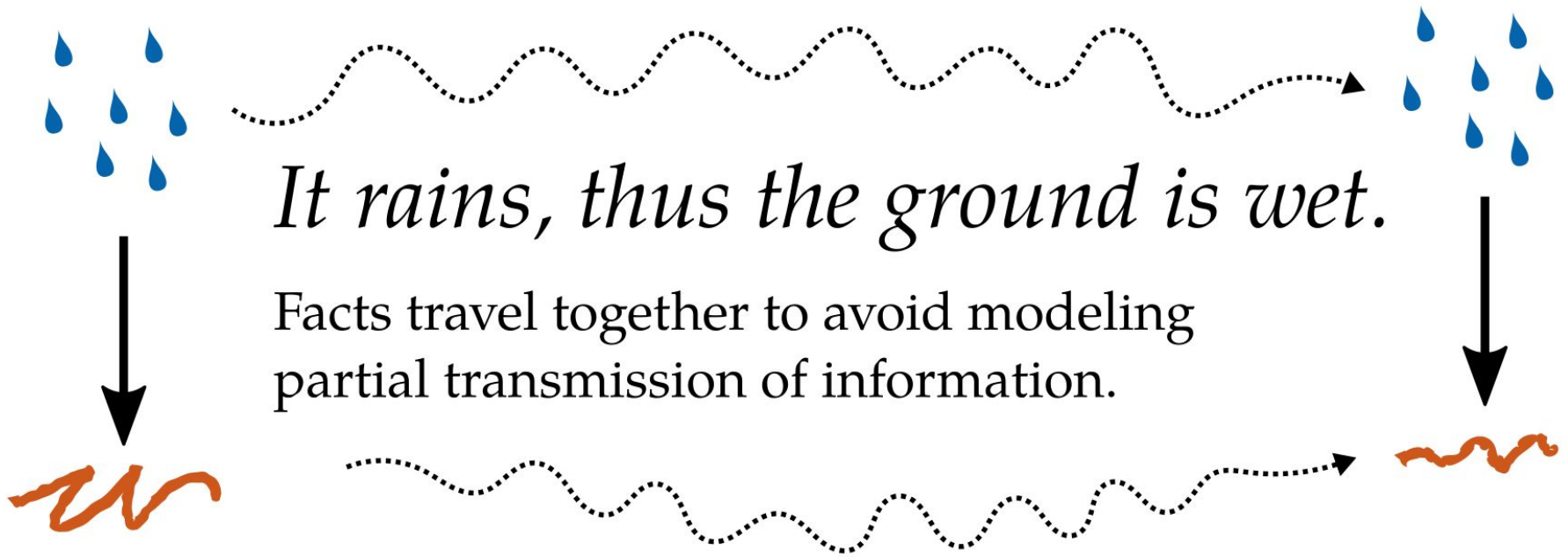
The background is a complex, multi-colored fractal pattern. It features a central circular motif with a pink and purple core, surrounded by concentric rings of yellow, blue, and red. Radiating from this center are numerous thin, dark lines that create a sense of depth and movement. The overall effect is a vibrant, almost hypnotic visual that draws the eye towards the center.

**perception**









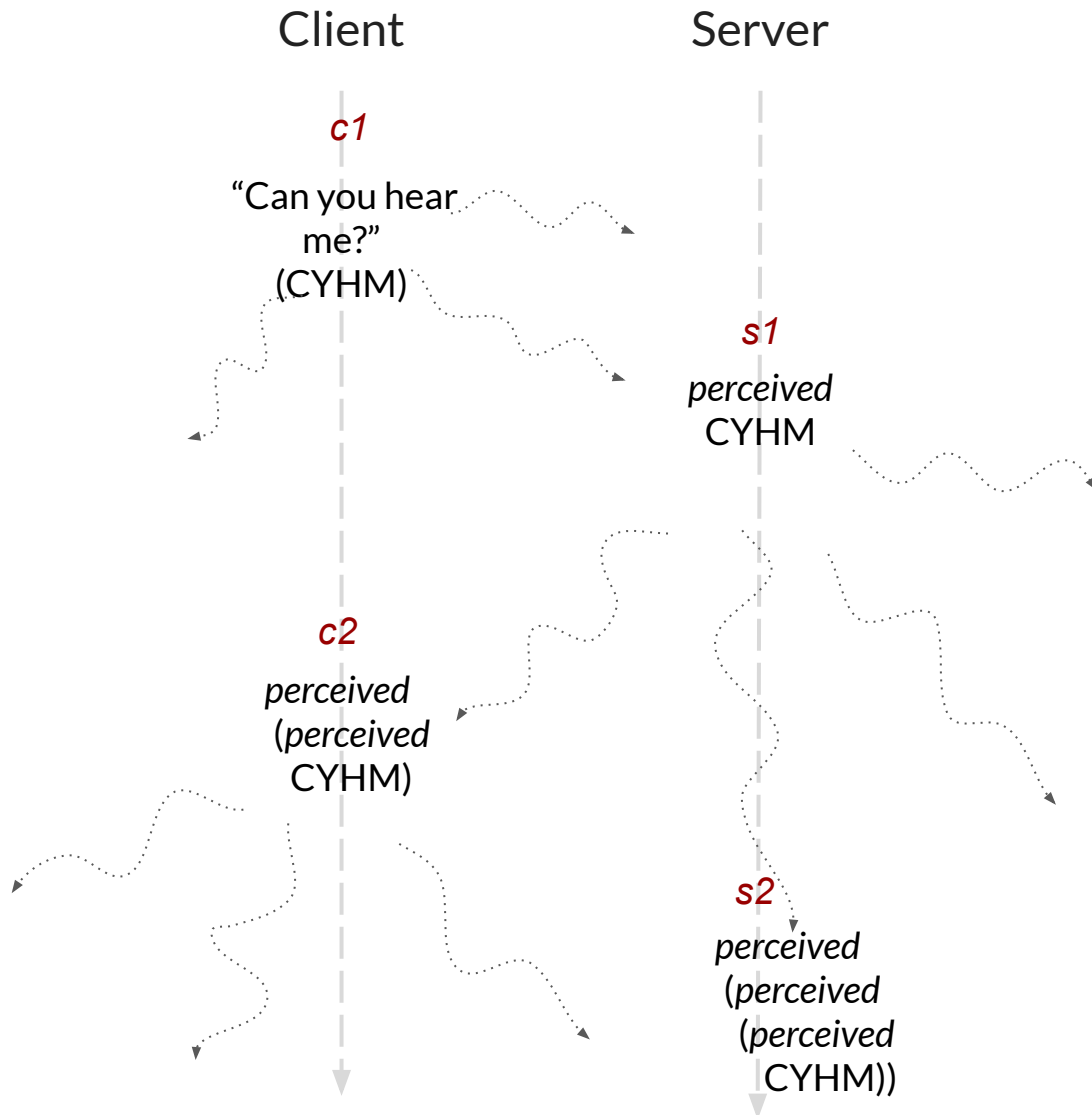


**all-knowing,  
transitive**

**perception**

**of facts  
and derivations**

# ping through the lens of perception



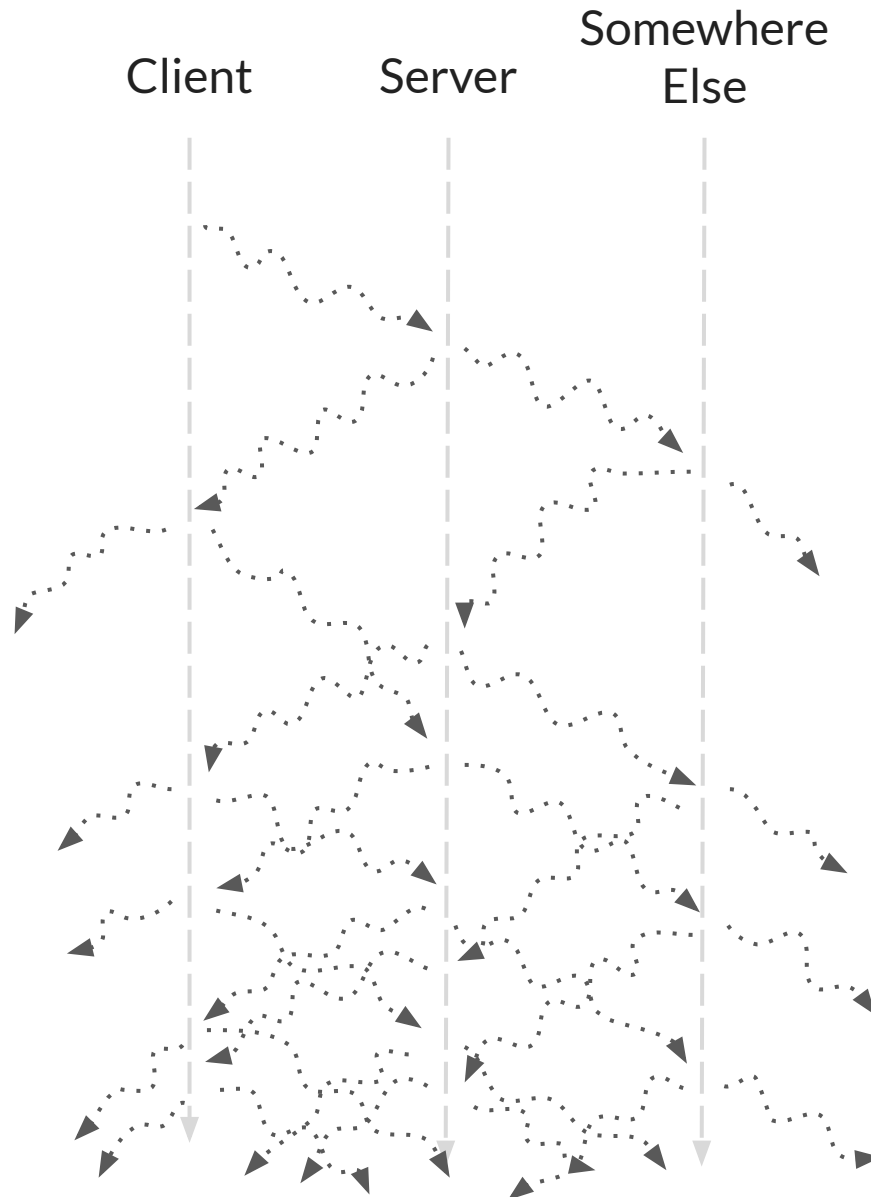
```
ping : Event ()  
ping =  
  perceptionsAt client  
    (perceptionsAt server  
      (canYouHearMe <> ping))
```

```
canYouHearMe : Event ()  
canYouHearMe = { c1 }
```

```
ping : Event ()  
ping = { c2, c3, c4, ... }
```



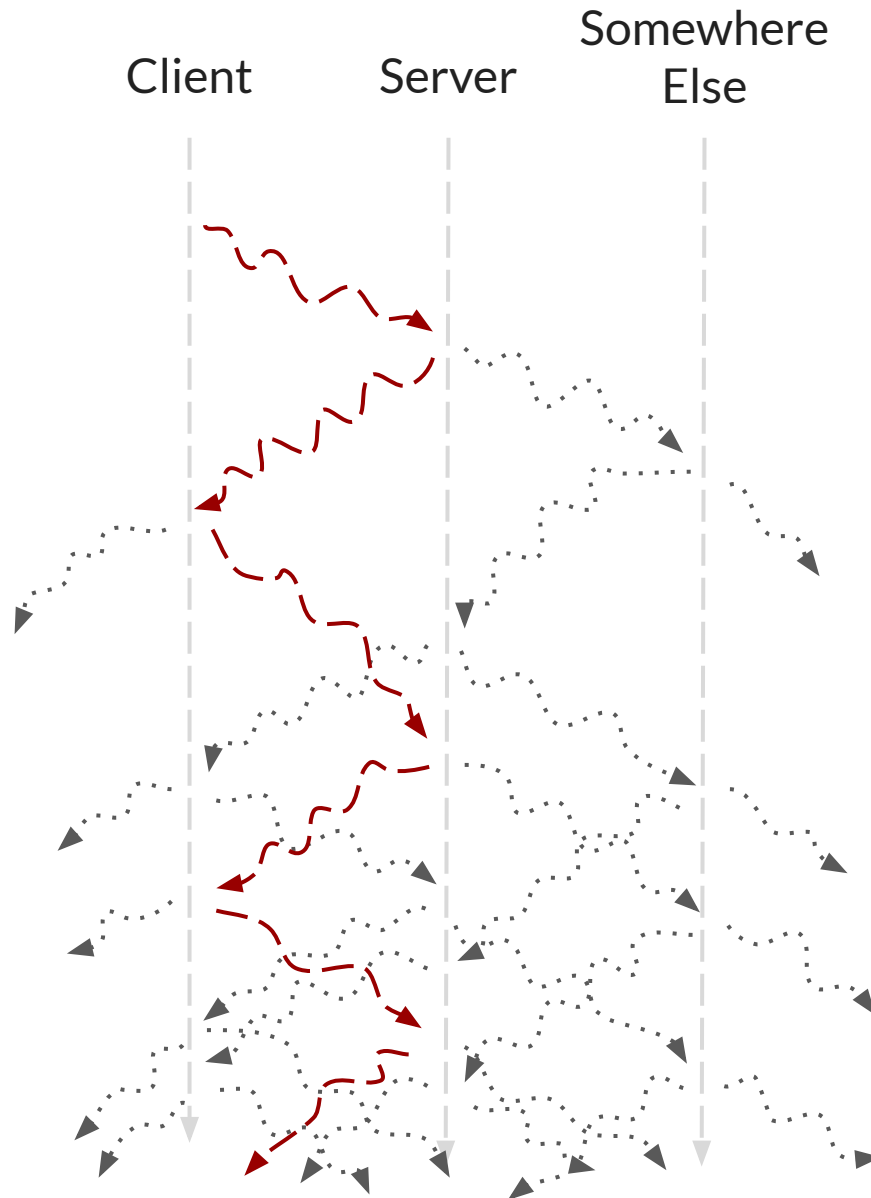
# Location-free programming



```
pingish : Event () → Event ()  
pingish start =  
  perceptions  
  (perceptions  
   (start <> pingish))
```

```
ping : Event () → Event ()  
ping start =  
  at client  
  (restrict [client, server]  
   (pingish start))
```

# Location-free programming



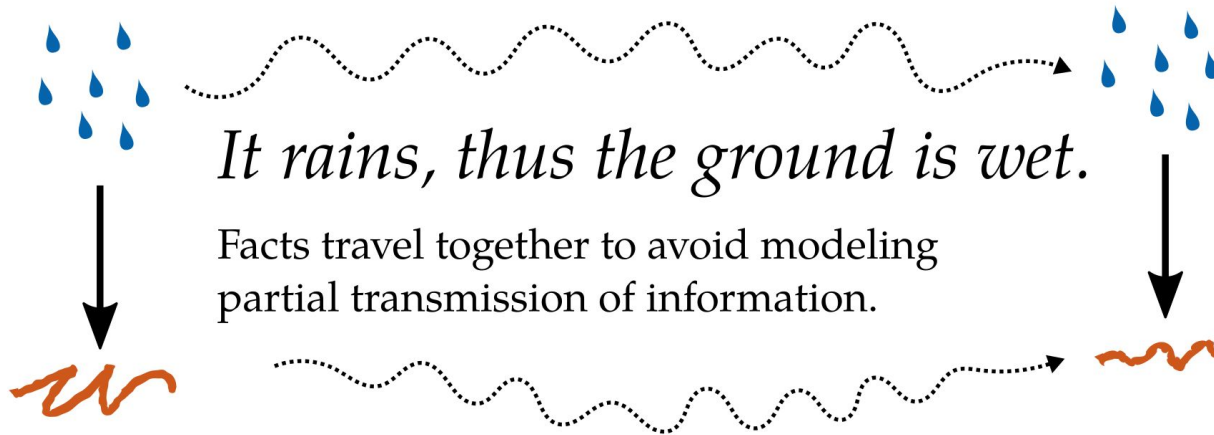
```
pingish : Event () → Event ()  
pingish start =  
  perceptions  
  (perceptions  
   (start <> pingish))
```

```
ping : Event () → Event ()  
ping start =  
  at client  
  (restrict [client, server]  
   (pingish start))
```

# Relativistic Functional Reactive Programming

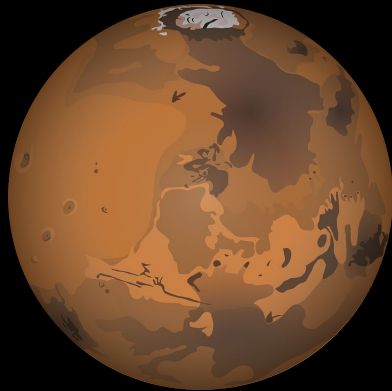
Behavior  $a = \text{Spacetime} \rightarrow a$

Event  $a = \text{Map Spacetime } a$



*Perception is transitive*

$$a < b \wedge b < c \Rightarrow a < c$$

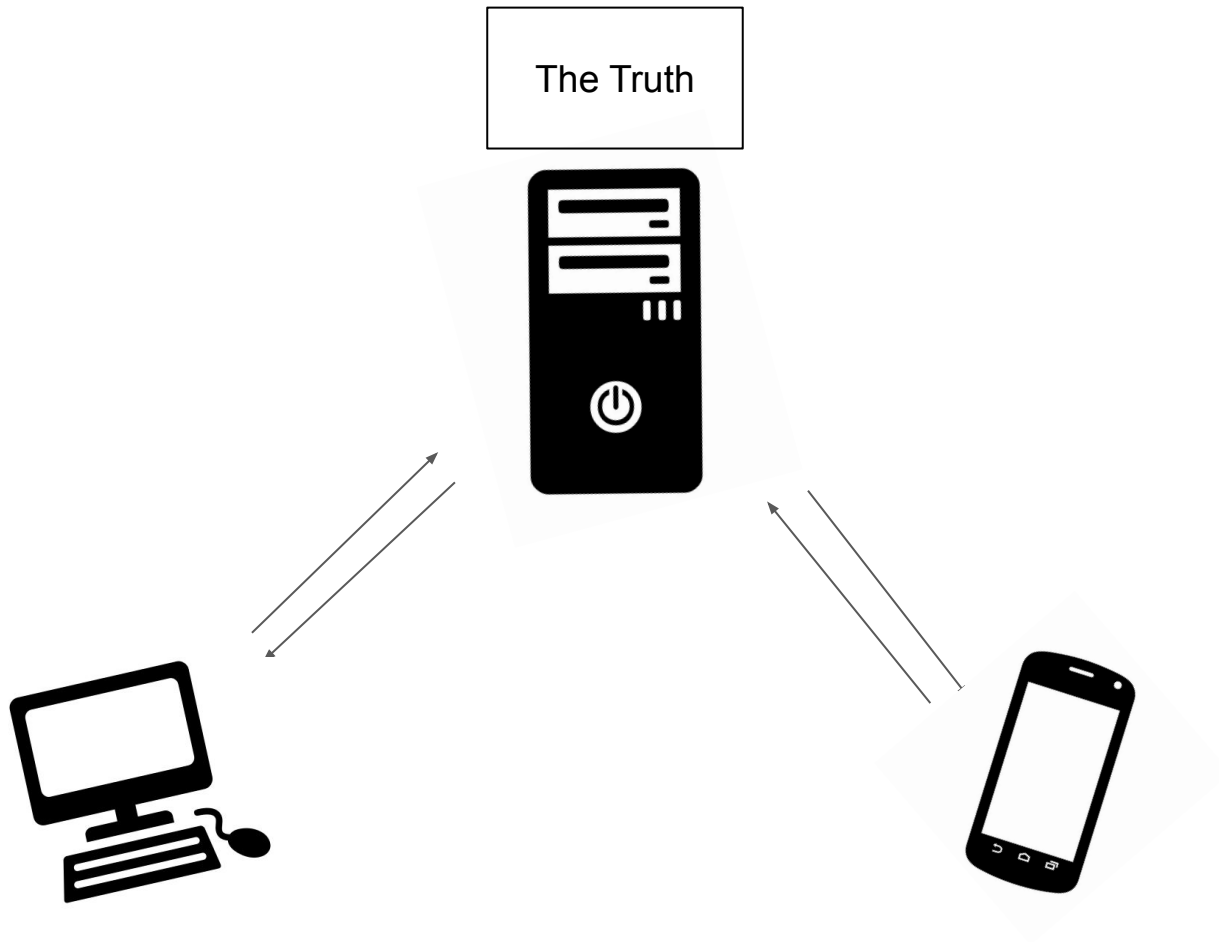


## Astro-do

- Get eggs
- Fix solar panels
- Send post card
- +** New task



*4-20 minutes to  
communicate*







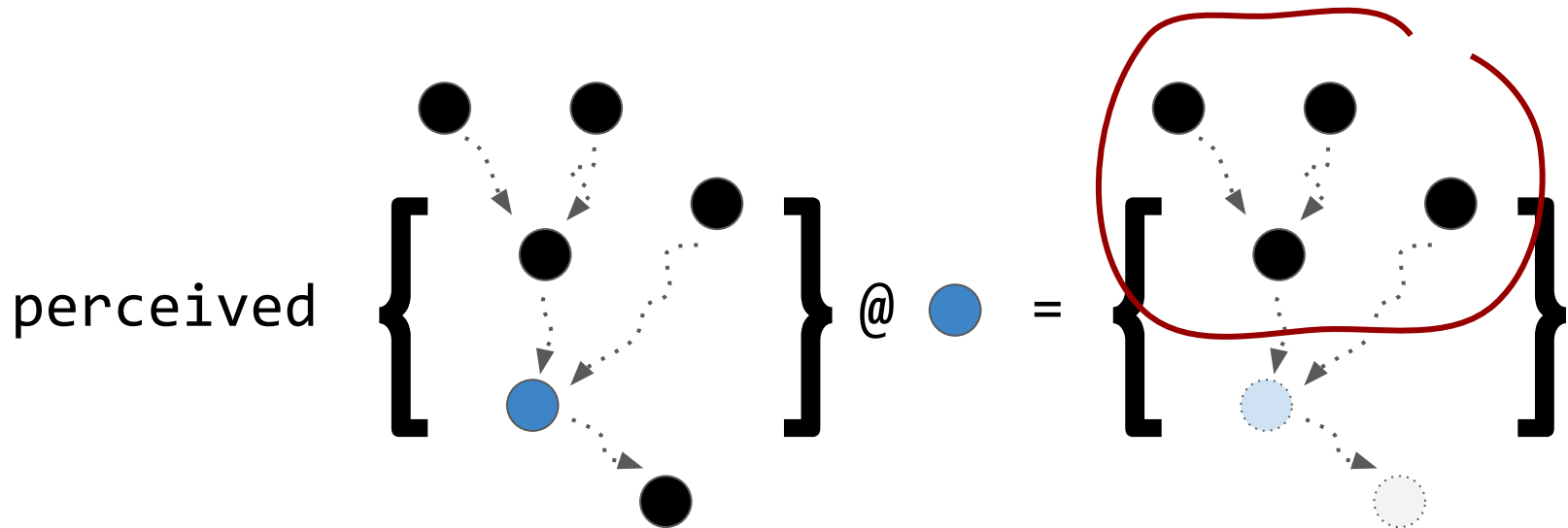




# *Strong Eventual Consistency*

*“predictably derive a result from known operations”*

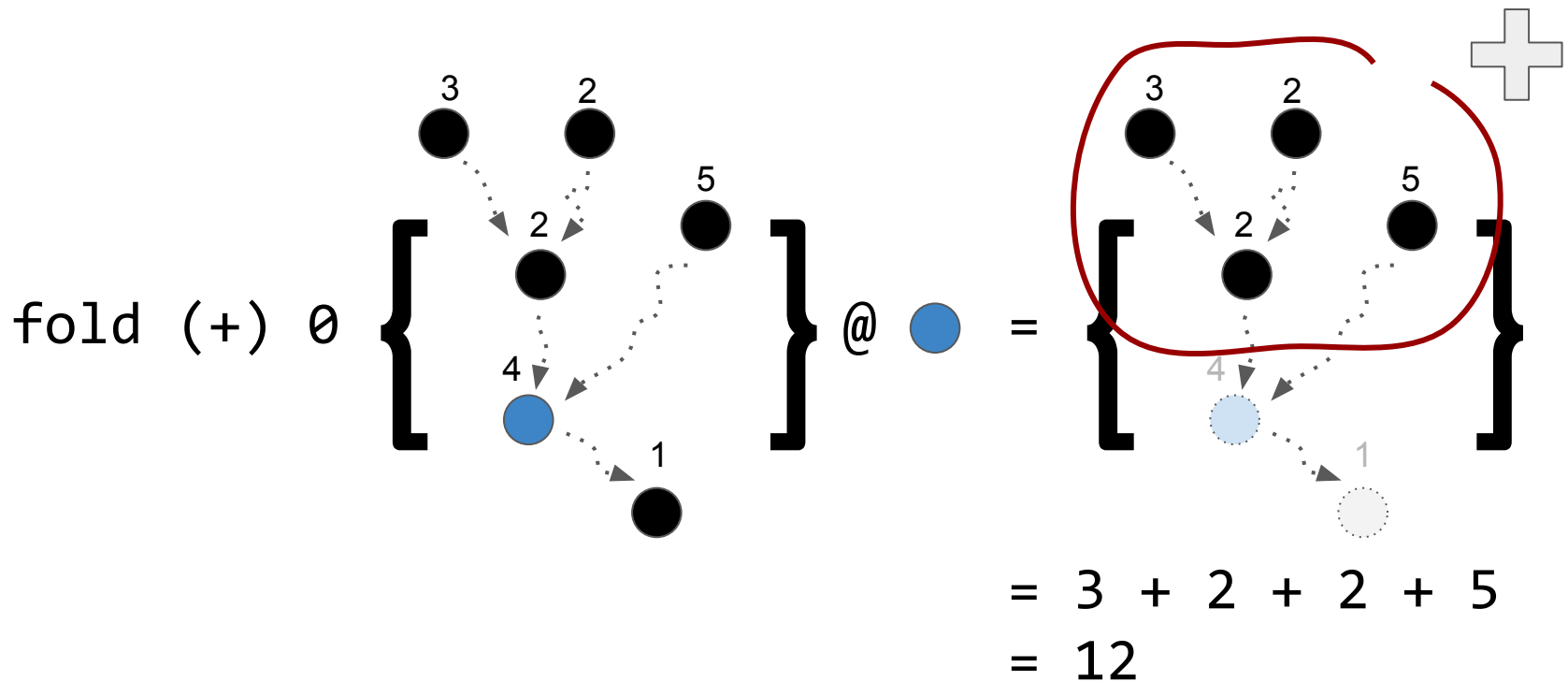
“predictably derive a result from known operations”



“predictably derive a result from known operations”

fold :: (a → a → a) → a → Event a → Behavior a

Commutative & associative combining function      initial value





### Astro-do

- Get eggs
- Fix solar panels
- Send post card
- New task*



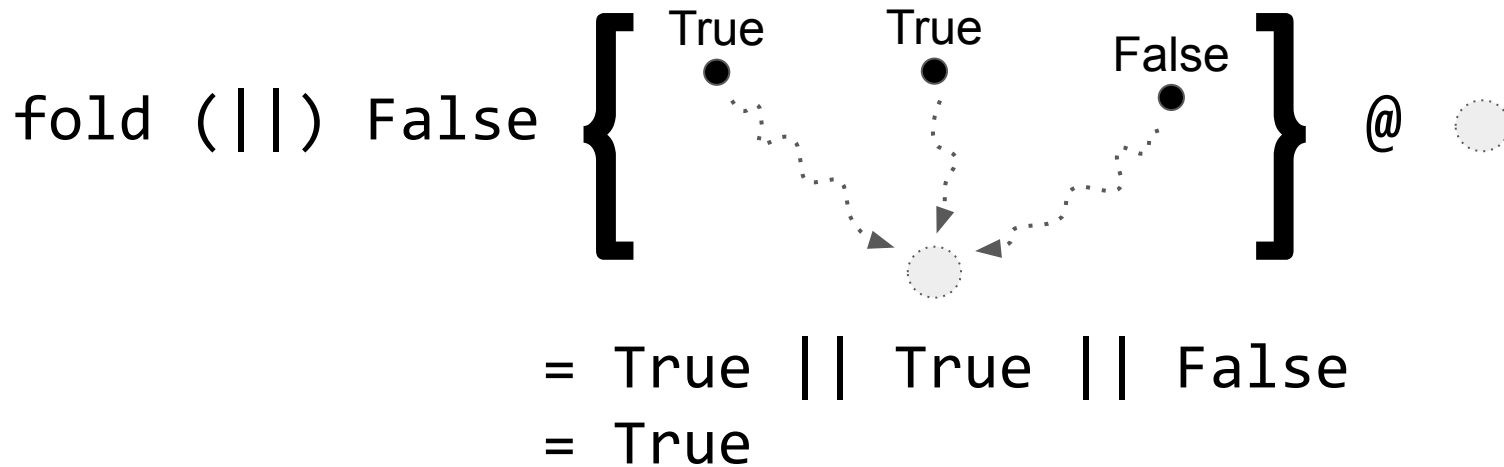
Fix solar panels





Fix solar panels

Is "Fix solar panels" deleted? ❌





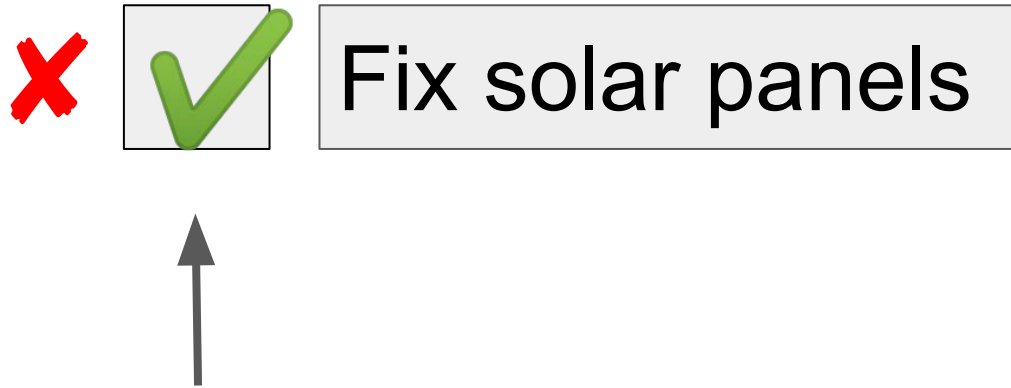
*Conflict-Free  
Replicated  
Data  
Types*

type Crdt operations values =

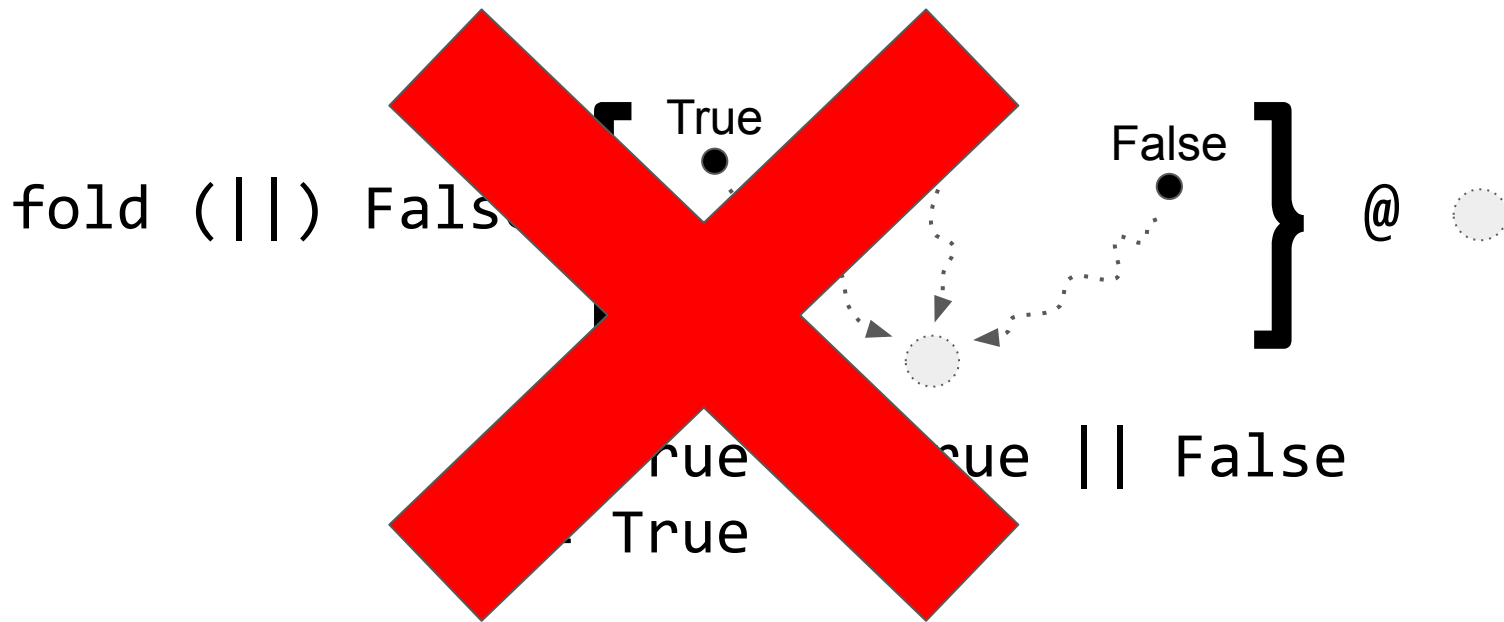
Event operations  $\rightarrow$  Behavior values

## *Enable-Once Flag CRDT*

```
eoflag :: Crdt Bool Bool  
eoflag = fold (||) False
```

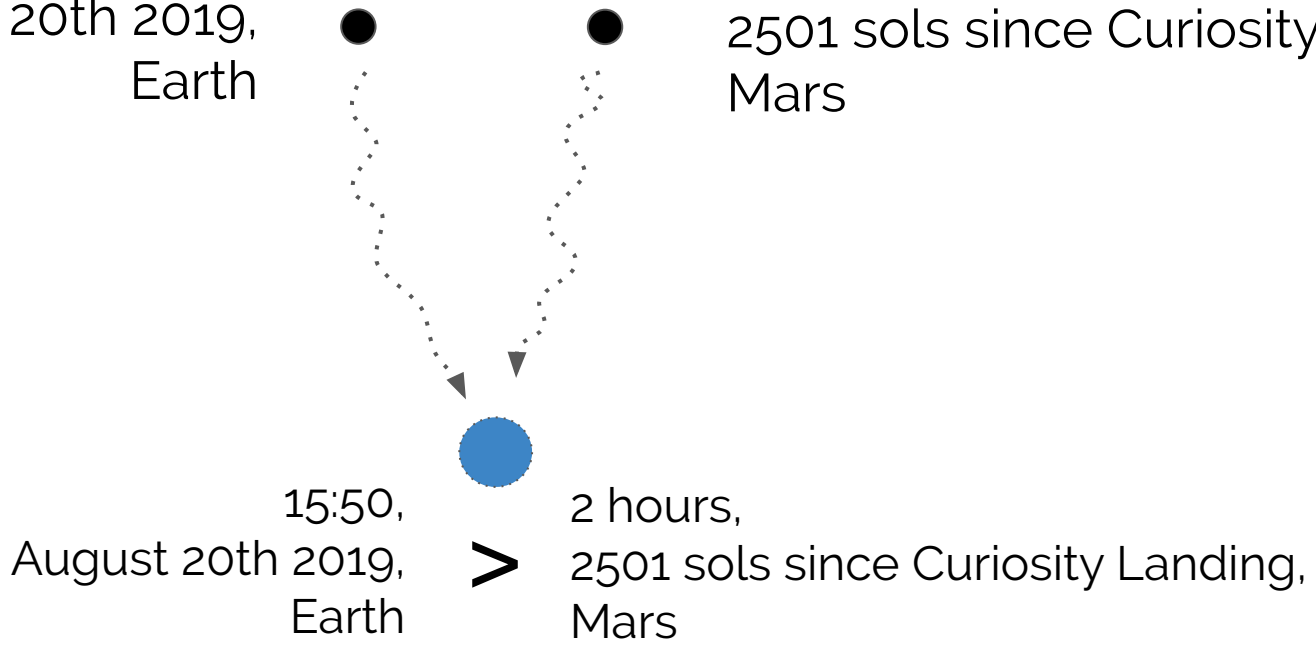


*Do the solar panels need fixing?*



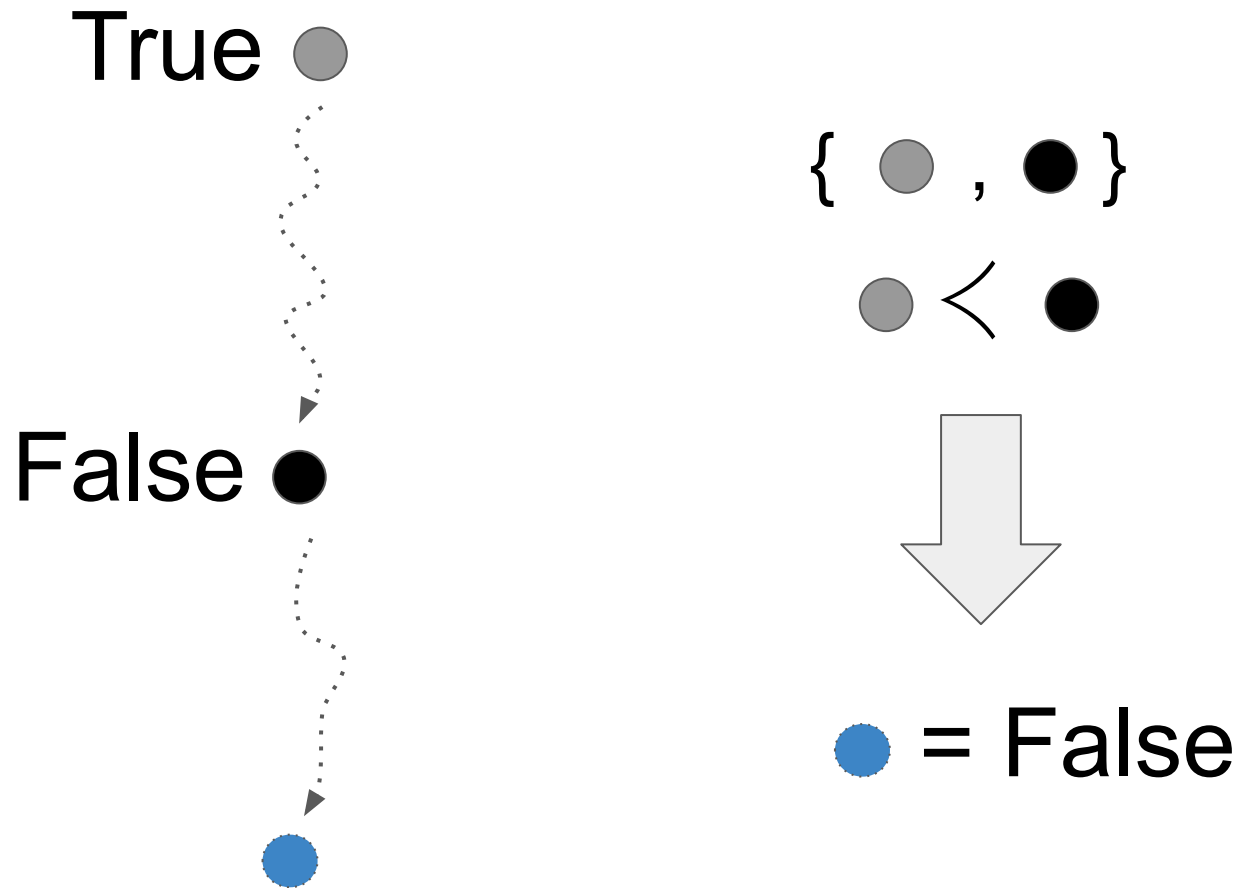
*“Overriding” decisions?*

15:50, August 20th 2019, Earth    **True**    **False**    2 hours, 2501 sols since Curiosity Landing, Mars



⇒ True

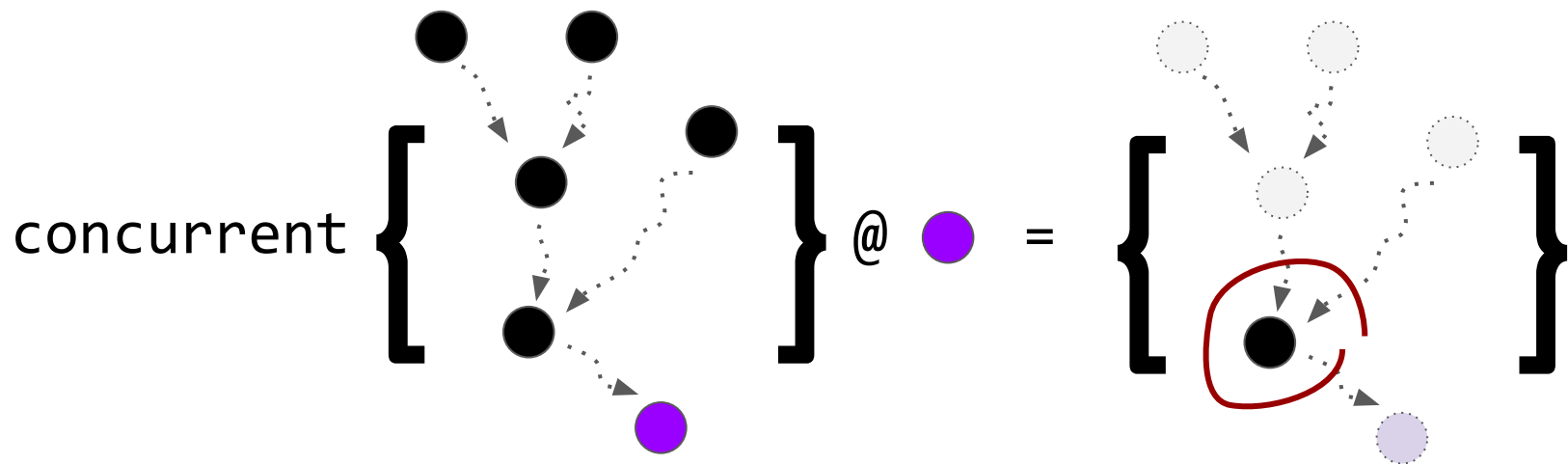
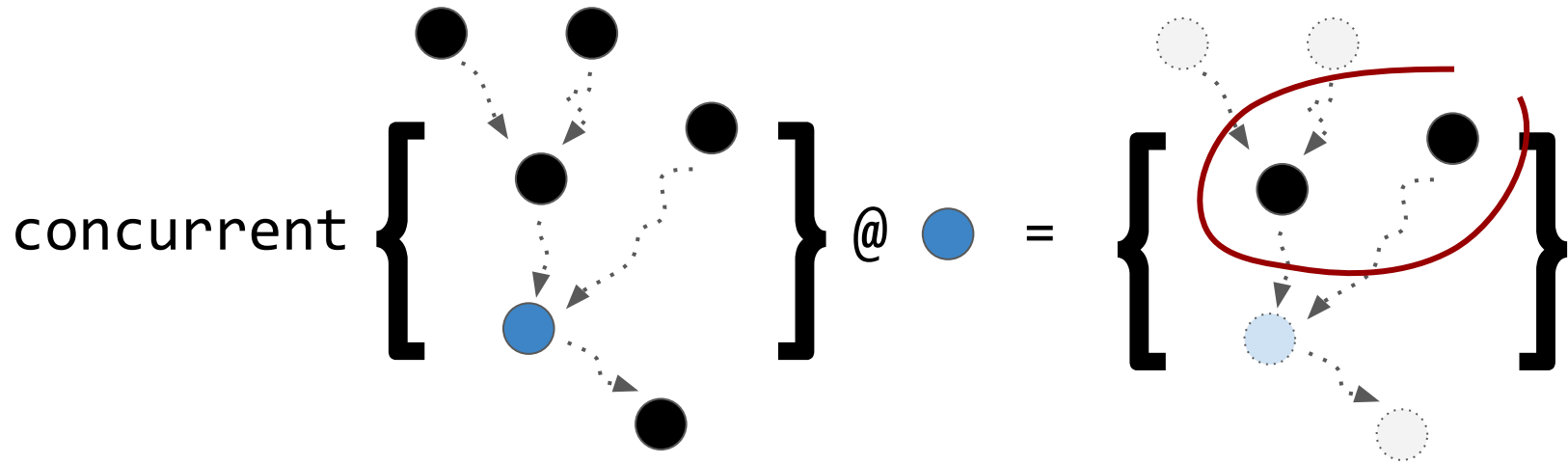
~~Last-Winner-Wins~~



*Concurrent events*

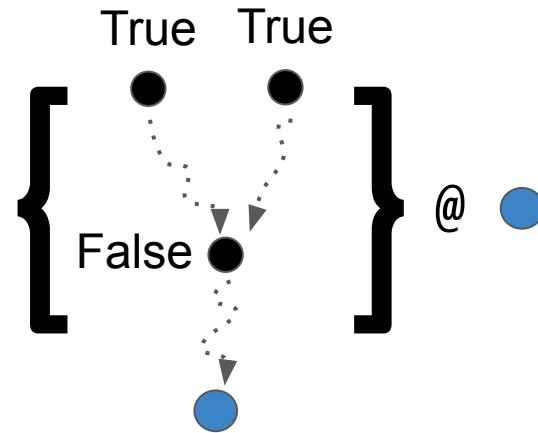


concurrent  $::$  Event  $a \rightarrow$  Behavior (Event  $a$ )



# Do the solar panels need fixing?

(eoflag =<< concurrent)  
= False



(=<<) :: Behavior a  $\rightarrow$  (a  $\rightarrow$  Behavior b)  $\rightarrow$  Behavior b

## *Enable-Once Flag CRDT*

```
eoflag :: Crdt Bool Bool
```

```
eoflag = fold (||) False
```

## *Enable-Wins Flag CRDT*

```
ewflag :: Crdt Bool Bool
```

```
ewflag = (eoflag =<< concurrent)
```



Fix solar panels



## Fix solar panels

1. Insert 'x' @ 10

≠

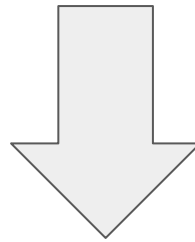
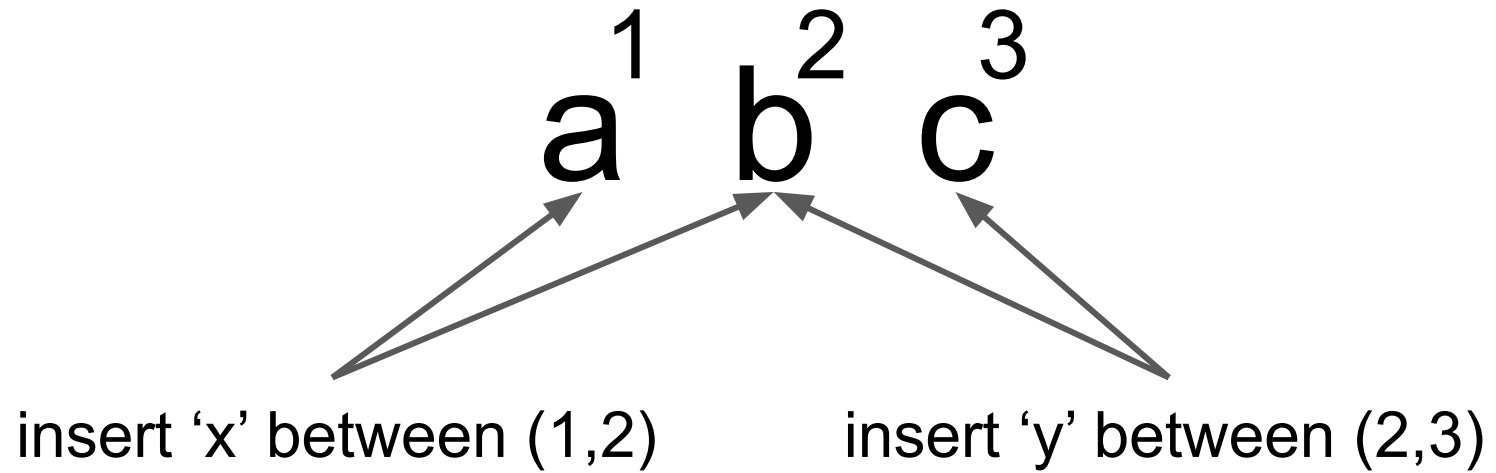
1. Insert 'y' @ 10

2. Insert 'y' @ 10

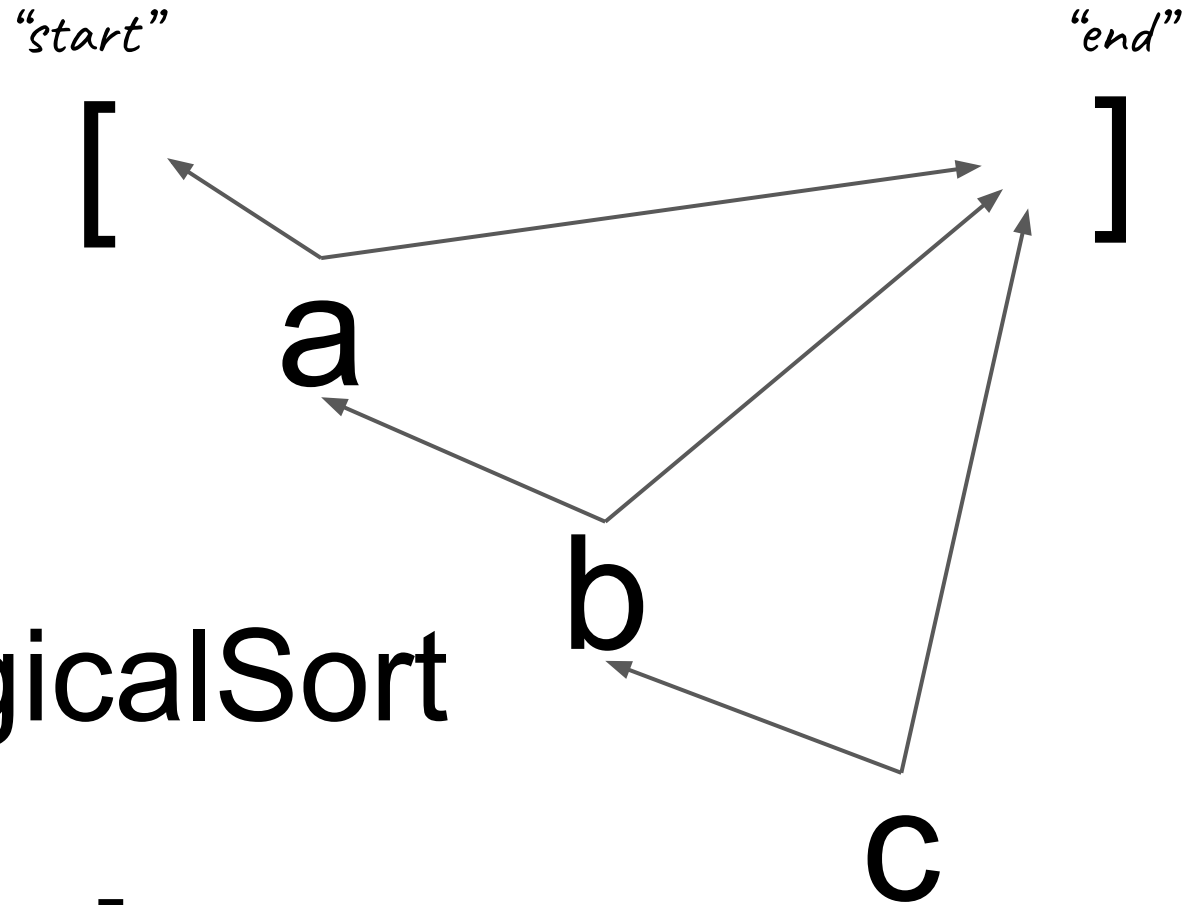
2. Insert 'x' @ 10

Fix solar xypanels

Fix solar yxpanels



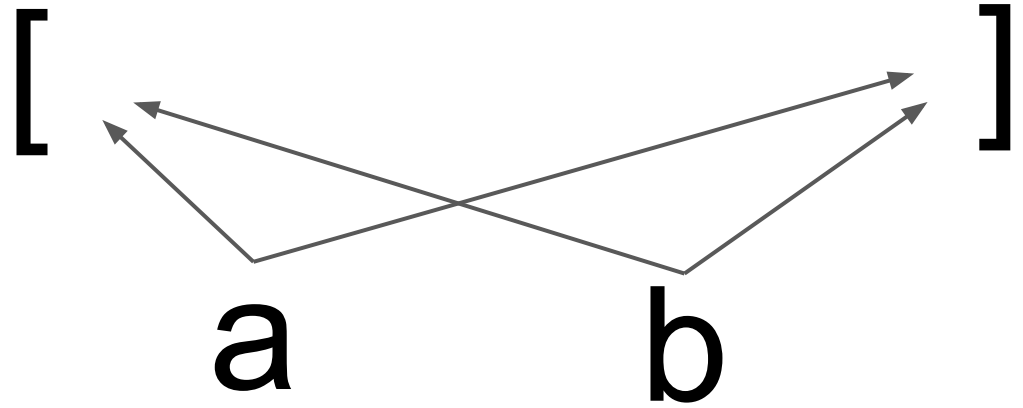
The resulting sequence after insertion is  $a^1 x^4 b^2 y^5 c^3$ .



topologicalSort

= [ a b c ]

topologicalSort



[ a b ] or [ b a ] ?

*Tie breaking on identifiers*



*Let's program sequences!*

```
sequence :: Event (Pos, Pos, a)
          → Behavior [(Id, a)]
```



```
data Pos = Start
         | Middle Id
         | End
```

```
type Id = Spacetime
```

```
tagWithSpacetime :: Event a
                  → Event (Spacetime, a)
```

```
sequence :: Event (Pos, Pos, a)
          → Behavior [(Id, a)]
```

```
sequence e =
```

```
  let idsE = tagWithSpacetime e
```

```
      graphB = fold Set.union Set.empty
```

```
              (mapE Set.singleton idsE)
```

```
  in mapB topologicalSort graphB
```

```
topologicalSort :: Set (Id, (Pos, Pos, a))
                 → [(Id, a)]
```

```
mapE :: (a → b) → Event a → Event b
```

```
mapB :: (a → b) → Behavior a → Behavior b
```

# Sequence with deletion

sequence :: Event (Pos, Pos, a)  
→ Behavior [(Id, a)]

$a = \text{Behavior} (\text{Bool}, a')$



Behavior [(Id, Behavior Bool a)]

filter + (= <<) ~ Behavior [(Id, a)]

enable-once  
flag

**Astro-do**

- ✗  Get eggs
- ✗  Fix solar panels
- ✗  Send post card
- + *New task*

✗  **Fix solar panels**

enable-wins  
flag

sequence +  
enable-once flag

# WIP

## Eventually Consistent

## RFRP

- Library UX for GUI
- Extending Reflex!  
<https://github.com/reflex-frp/reflex>  
=> Production quality P2P apps
- Hard problems (PhD)

# Sequence with deletion

sequence :: Event (Pos, Pos, a)  
→ Behavior [(Id, a)]

$a = \text{Behavior} (\text{Bool}, a')$



Behavior [(Id, Behavior Bool a)]

filter + (= <<) ~ Behavior [(Id, a)]

# Relativistic Functional Reactive Programming

Behavior  $a = \text{Spacetime} \rightarrow a$

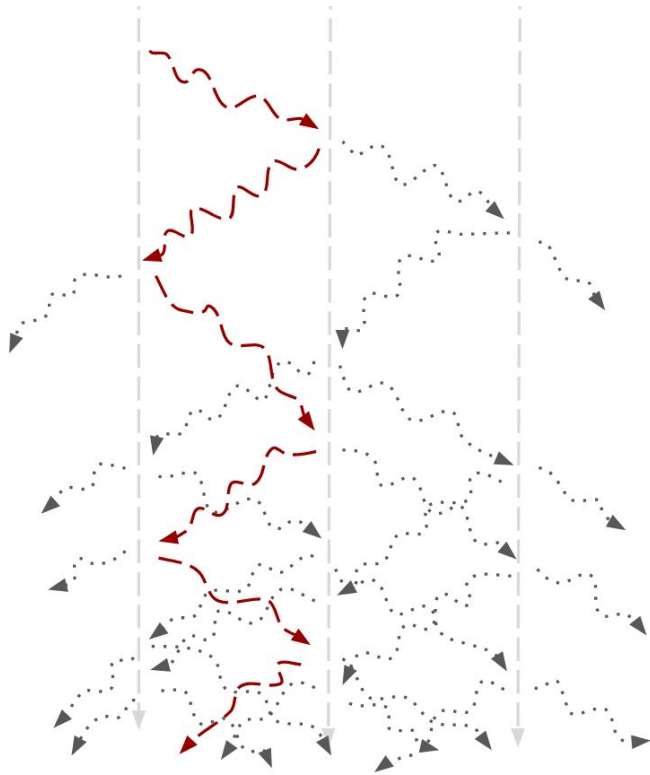
Event  $a = \text{Map Spacetime } a$



@aidylns



@parenthetical



`fold :: (a → a → a) (Commutative & associative)`  
`→ a`  
`→ Event a`  
`→ Behavior a`

`concurrent :: Event a`  
`→ Behavior (Event a)`

*Peer-to-peer apps for free!*



*Probabilistic*

*Relativistic*

*Functional Reactive Programming*

Behavior  $a \rightarrow (\text{Spacetime}, \text{Probability}, a)$

temperature  $:: \text{Spacetime} \rightarrow \text{Kelvin}$

# Astro-do

- Get eggs
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- Send post card
- New task*

Get eggs

Fix solar panels